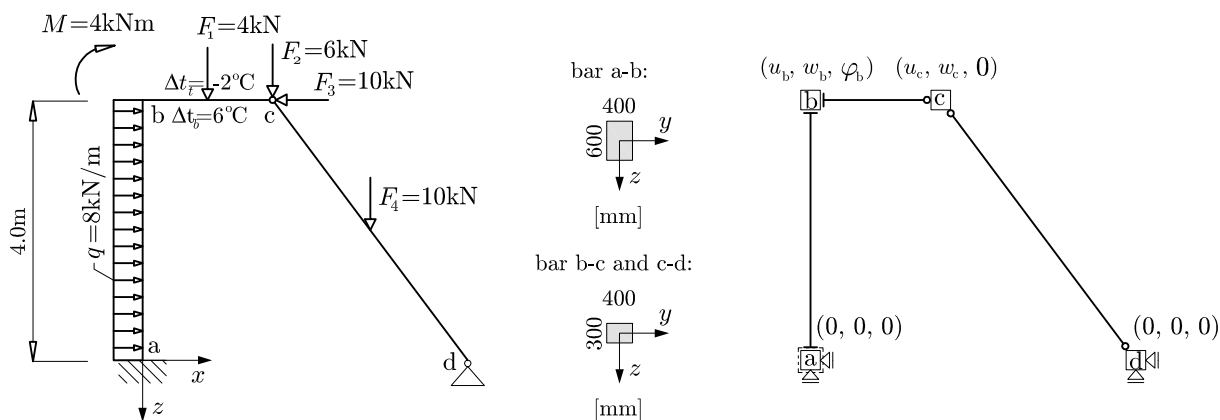


1.2 2D rám

Obecnou deformační metodou vypočítejte a vykreslete vnitřní síly na rovinném rámu na obr. 7. Materiálové parametry jsou: modul pružnosti $E = 24 \text{ GPa}$ a koeficient teplotní roztažnosti $\alpha_t = 10^{-5} \text{ K}^{-1}$.



Obrázek 7: Vlevo: 2D rám a vpravo: výpočtový model.

Průřezová plocha prutů

$$A_{ab} = b \cdot h = 0.4 \cdot 0.6 = 0.24 \text{ m}^2$$

$$A_{bc} = A_{cd} = b \cdot h = 0.4 \cdot 0.3 = 0.12 \text{ m}^2$$

Momenty setrvačnosti

$$I_y^{ab} = \frac{1}{12} \cdot b \cdot h^3 = \frac{1}{12} \cdot 0.4 \cdot 0.6^3 = 0.0072 \text{ m}^4$$

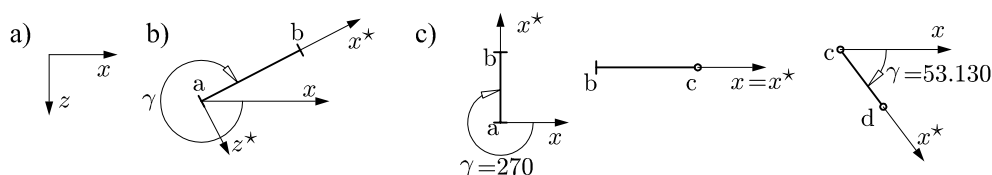
$$I_y^{bc} = I_y^{cd} = \frac{1}{12} \cdot b \cdot h^3 = \frac{1}{12} \cdot 0.4 \cdot 0.3^3 = 0.0009 \text{ m}^4$$

1. stupeň přetvárné neurčitosti

$$n_p = 5$$

2. vektor neznámých deformací a styčnických sil

$$\{\mathbf{r}\} = \begin{Bmatrix} u_b \\ w_b \\ \varphi_b \\ u_c \\ w_c \end{Bmatrix} \quad \{\mathbf{S}\} = \begin{Bmatrix} 0 \\ 0 \\ -4\,000 \\ -10\,000 \\ 6\,000 \end{Bmatrix} \text{ [N, Nm]} \quad (9)$$



Obrázek 8: a) globální souřadný systém xz , b) lokální souřadný systém prutu x^*z^* a určení úhlu γ (ve směru hodinových ručiček) c) úhel γ pro pruty a-b, b-c a c-d

3. Globální matice tuhosti

(a) prut a-b — tab. 11.4a, úhel $\gamma = 270^\circ \Rightarrow s = -1, c = 0$

$$[\mathbf{k}_{ab}] = \begin{pmatrix} u_a & w_a & \varphi_a & u_b & w_b & \varphi_b \\ \cdot & \cdot & \cdot & -32.4 & 0 & -64.8 \\ \cdot & \cdot & \cdot & 0 & -1440 & 0 \\ \cdot & \cdot & \cdot & 64.8 & 0 & 86.4 \\ \cdot & \cdot & \cdot & 32.4 & 0 & 64.8 \\ \cdot & \cdot & \cdot & 0 & 1440 & 0 \\ \cdot & \cdot & \cdot & 64.8 & 0 & 172.8 \end{pmatrix} \begin{matrix} u_a \\ w_a \\ \varphi_a \\ u_b \\ w_b \\ \varphi_b \end{matrix} \left[\cdot 10^6 \frac{\text{N}}{\text{m}} \right]$$

(b) prut b-c – lokální souřadný systém je totožný s globálním — můžeme tedy použít tab. 11.3b

$$[\mathbf{k}_{bc}] = [\mathbf{k}_{bc}^*] = \begin{pmatrix} u_b & w_b & \varphi_b & u_c & w_c & \varphi_c \\ 1440 & 0 & 0 & -1440 & 0 & 0 \\ 0 & 8.1 & -16.2 & 0 & -8.1 & 0 \\ 0 & -16.2 & 32.4 & 0 & 16.2 & 0 \\ -1440 & 0 & 0 & 1440 & 0 & 0 \\ 0 & -8.1 & 16.2 & 0 & 8.1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \begin{matrix} u_b \\ w_b \\ \varphi_b \\ u_c \\ w_c \\ \varphi_c \end{matrix} \left[\cdot 10^6 \frac{\text{N}}{\text{m}} \right]$$

(c) prut c-d — tab. 11.4d, úhel $\gamma = 53.130^\circ \Rightarrow s = \frac{4}{5}, c = \frac{3}{5}$

$$[\mathbf{k}_{cd}] = \begin{pmatrix} u_c & w_c & \varphi_c & u_d & w_d & \varphi_d \\ 207.36 & 276.48 & \cdot & \cdot & \cdot & \cdot \\ 276.48 & 368.64 & \cdot & \cdot & \cdot & \cdot \\ 0 & 0 & \cdot & \cdot & \cdot & \cdot \\ -207.36 & -276.48 & \cdot & \cdot & \cdot & \cdot \\ -276.48 & -368.64 & \cdot & \cdot & \cdot & \cdot \\ 0 & 0 & \cdot & \cdot & \cdot & \cdot \end{pmatrix} \begin{matrix} u_c \\ w_c \\ \varphi_c \\ u_d \\ w_d \\ \varphi_d \end{matrix} \left[\cdot 10^6 \frac{\text{N}}{\text{m}} \right]$$

(d) Globální matice tuhosti prutového systému

$$[\mathbf{k}] = \begin{pmatrix} u_b & w_b & \varphi_b & u_c & w_c \\ 32.4 + 1440 & 0 + 0 & 64.8 + 0 & -1440 & 0 \\ 0 + 0 & 1440 + 8.1 & 0 + (-16.2) & 0 & -8.1 \\ 64.8 + 0 & 0 + (-16.2) & 172.8 + 32.4 & 0 & 16.2 \\ -1440 & 0 & 0 & 1440 + 207.36 & 0 + 276.48 \\ 0 & -8.1 & 16.2 & 0 + 276.48 & 8.1 + 368.64 \end{pmatrix} \begin{matrix} u_b \\ w_b \\ \varphi_b \\ u_c \\ w_c \end{matrix} \left[\cdot 10^6 \frac{\text{N}}{\text{m}} \right]$$

$$[\mathbf{k}] = \begin{pmatrix} u_b & w_b & \varphi_b & u_c & w_c \\ 1472.4 & 0 & 64.8 & -1440 & 0 \\ 0 & 1448.1 & -16.2 & 0 & -8.1 \\ 64.8 & -16.2 & 205.2 & 0 & 16.2 \\ -1440 & 0 & 0 & 1647.36 & 276.48 \\ 0 & -8.1 & 16.2 & 276.48 & 376.74 \end{pmatrix} \begin{matrix} u_b \\ w_b \\ \varphi_b \\ u_c \\ w_c \end{matrix} \left[\cdot 10^6 \frac{\text{N}}{\text{m}} \right]$$

4. Lokální primární vektor koncových sil

(a) prut a-b — tab. 11.2a (tab. 14.10 řádek 13)

$$\{\bar{\mathbf{R}}_{ab}^*\} = \begin{Bmatrix} \bar{X}_{ab}^* \\ \bar{Z}_{ab}^* \\ \bar{M}_{ab}^* \\ \bar{X}_{ba}^* \\ \bar{Z}_{ba}^* \\ \bar{M}_{ba}^* \end{Bmatrix} = \begin{Bmatrix} 0 \\ -16 \\ 10.\bar{6} \\ 0 \\ -16 \\ -10.\bar{6} \end{Bmatrix} [\cdot 10^3 \text{ N, Nm}] \quad (10)$$

– transformace do globálního souřadného systému

$$\{\bar{\mathbf{R}}_{ab}\} = \begin{Bmatrix} \bar{X}_{ab} \\ \bar{Z}_{ab} \\ \bar{M}_{ab} \\ \bar{X}_{ba} \\ \bar{Z}_{ba} \\ \bar{M}_{ba} \end{Bmatrix} = \begin{Bmatrix} -16 \\ 0 \\ 10.\bar{6} \\ -16 \\ 0 \\ -10.\bar{6} \end{Bmatrix} [\cdot 10^3 \text{ N, Nm}] \quad (11)$$

(b) prut b-c — síla F_1 : tab. 11.2c (tab. 14.11 řádek 2) a teplotní zatížení t : tab. 11.5b

$$\{\bar{\mathbf{R}}_{bc}^*\}_{F_1} = \{\bar{\mathbf{R}}_{bc}\}_{F_1} = \begin{Bmatrix} 0 \\ -2.75 \\ 1.5 \\ 0 \\ -1.25 \\ 0 \end{Bmatrix} [\cdot 10^3 \text{ N, Nm}] \quad (12)$$

$$\{\bar{\mathbf{R}}_{bc}^*\}_t = \{\bar{\mathbf{R}}_{bc}\}_t = \begin{Bmatrix} 57.6 \\ -4.32 \\ 8.64 \\ -57.6 \\ 4.32 \\ 0 \end{Bmatrix} [\cdot 10^3 \text{ N, Nm}] \quad (13)$$

$$\{\bar{\mathbf{R}}_{bc}^*\} = \{\bar{\mathbf{R}}_{bc}\} = \begin{Bmatrix} \bar{X}_{bc}^* \\ \bar{Z}_{bc}^* \\ \bar{M}_{bc}^* \\ \bar{X}_{cb}^* \\ \bar{Z}_{cb}^* \\ \bar{M}_{cb}^* \end{Bmatrix} = \begin{Bmatrix} 57.6 \\ -7.07 \\ 10.14 \\ -57.6 \\ 3.07 \\ 0 \end{Bmatrix} [\cdot 10^3 \text{ N, Nm}] \quad (14)$$

(c) prut c-d — stejné jako prostě podepřený nosník

$$\{\bar{\mathbf{R}}_{cd}^*\} = \begin{Bmatrix} \bar{X}_{cd}^* \\ \bar{Z}_{cd}^* \\ \bar{M}_{cd}^* \\ \bar{X}_{dc}^* \\ \bar{Z}_{dc}^* \\ \bar{M}_{dc}^* \end{Bmatrix} = \begin{Bmatrix} -4 \\ -3 \\ 0 \\ -4 \\ -3 \\ 0 \end{Bmatrix} [\cdot 10^3 \text{ N, Nm}] \quad (15)$$

– transformace do globálních souřadnic

$$\{\bar{\mathbf{R}}_{cd}\} = \begin{Bmatrix} \bar{X}_{cd} \\ \bar{Z}_{cd} \\ \bar{M}_{cd} \\ \bar{X}_{dc} \\ \bar{Z}_{dc} \\ \bar{M}_{dc} \end{Bmatrix} = \begin{Bmatrix} 0 \\ -5 \\ 0 \\ 0 \\ -5 \\ 0 \end{Bmatrix} [\cdot 10^3 \text{ N, Nm}] \quad (16)$$

(d) Primární vektor prutového systému

$$\{\bar{\mathbf{R}}\} = \begin{Bmatrix} -16 + 57.6 \\ 0 + (-7.07) \\ -10.6 + 10.14 \\ -57.6 + 0 \\ 3.07 + (-5) \end{Bmatrix} \cdot 10^3 = \begin{Bmatrix} 41.6 \\ -7.07 \\ -0.526 \\ -57.6 \\ -1.93 \end{Bmatrix} [\cdot 10^3 \text{ N, Nm}] \quad (17)$$

5. Zatěžovací vektor

$$\{\mathbf{F}\} = \{\mathbf{S}\} - \{\bar{\mathbf{R}}\} = \begin{Bmatrix} 0 \\ 0 \\ -4 \\ -10 \\ 6 \end{Bmatrix} \cdot 10^3 - \begin{Bmatrix} 41.6 \\ -7.07 \\ -0.526 \\ -57.6 \\ -1.93 \end{Bmatrix} \cdot 10^3 = \begin{Bmatrix} -41.6 \\ 7.07 \\ -3.473 \\ 47.6 \\ 7.93 \end{Bmatrix} [\cdot 10^3 \text{ N, Nm}] \quad (18)$$

6. Soustava rovnic

$$[\mathbf{k}] \cdot \{\mathbf{r}\} = \{\mathbf{F}\} \quad (19)$$

$$\begin{pmatrix} 1472.4 & 0 & 64.8 & -1440 & 0 \\ 0 & 1448.1 & -16.2 & 0 & -8.1 \\ 64.8 & -16.2 & 205.2 & 0 & 16.2 \\ -1440 & 0 & 0 & 1647.36 & 276.48 \\ 0 & -8.1 & 16.2 & 276.48 & 376.74 \end{pmatrix} \cdot 10^6 \cdot \begin{Bmatrix} u_b \\ w_b \\ \varphi_b \\ u_c \\ w_c \end{Bmatrix} = \begin{Bmatrix} -41.6 \\ 7.07 \\ -3.473 \\ 47.6 \\ 7.93 \end{Bmatrix} \cdot 10^3$$

$$\begin{Bmatrix} u_b \\ w_b \\ \varphi_b \\ u_c \\ w_c \end{Bmatrix} = \begin{Bmatrix} 39.171 \\ 4.429 \\ -26.783 \\ 67.736 \\ -27.414 \end{Bmatrix} [\cdot 10^{-6} \text{ m, rad}]$$

7. Vektor koncových sil prutu

$$\{\mathbf{R}_{ab}\} = \{\bar{\mathbf{R}}_{ab}\} + \{\hat{\mathbf{R}}_{ab}\} = \{\bar{\mathbf{R}}_{ab}\} + [\mathbf{k}_{ab}] \{\mathbf{r}_{ab}\} \quad (20)$$

$$\{\hat{\mathbf{R}}_{ab}\} = \begin{pmatrix} . & . & . & -32.4 & 0 & -64.8 \\ . & . & . & 0 & -1440 & 0 \\ . & . & . & 64.8 & 0 & 86.4 \\ . & . & . & 32.4 & 0 & 64.8 \\ . & . & . & 0 & 1440 & 0 \\ . & . & . & 64.8 & 0 & 172.8 \end{pmatrix} \cdot \begin{Bmatrix} 0 \\ 0 \\ 0 \\ 39.171 \\ 4.429 \\ -26.783 \end{Bmatrix} = \begin{Bmatrix} 466.398 \\ -6377.76 \\ 224.230 \\ -466.398 \\ 6377.76 \\ -2089.822 \end{Bmatrix} [\text{N, Nm}]$$

$$\{\hat{\mathbf{R}}_{bc}\} = \begin{pmatrix} 1440 & 0 & 0 & -1440 & 0 & 0 \\ 0 & 8.1 & -16.2 & 0 & -8.1 & 0 \\ 0 & -16.2 & 32.4 & 0 & 16.2 & 0 \\ -1440 & 0 & 0 & 1440 & 0 & 0 \\ 0 & -8.1 & 16.2 & 0 & 8.1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} 39.171 \\ 4.429 \\ -26.783 \\ 67.736 \\ -27.414 \\ 0 \end{pmatrix} = \begin{pmatrix} -41133.6 \\ 691.813 \\ -1383.626 \\ 41133.6 \\ -691.813 \\ 0 \end{pmatrix} \text{ [N, Nm]}$$

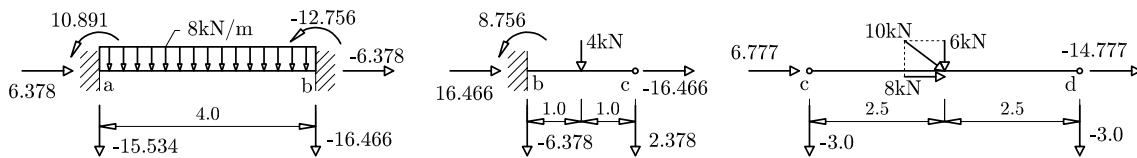
$$\{\hat{\mathbf{R}}_{cd}\} = \begin{pmatrix} 207.36 & 276.48 & . & . & . & . \\ 276.48 & 368.64 & . & . & . & . \\ 0 & 0 & . & . & . & . \\ -207.36 & -276.48 & . & . & . & . \\ -276.48 & -368.64 & . & . & . & . \\ 0 & 0 & . & . & . & . \end{pmatrix} \cdot \begin{pmatrix} 67.736 \\ -27.414 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 6466.314 \\ 8621.752 \\ 0 \\ -6466.314 \\ -8621.752 \\ 0 \end{pmatrix} \text{ [N, Nm]}$$

$$\{\mathbf{R}_{ab}\} = \begin{pmatrix} -15533.602 \\ -6377.76 \\ 10890.89\bar{6} \\ -16466.398 \\ 6377.76 \\ -12765.488\bar{6} \end{pmatrix} \xrightarrow{\text{transform}} \{\mathbf{R}_{ab}^*\} = \begin{pmatrix} 6377.76 \\ -15533.6 \\ 10890.89\bar{6} \\ -6377.76 \\ -16466.398 \\ -12765.488\bar{6} \end{pmatrix} \text{ [N, Nm]}$$

$$\{\mathbf{R}_{bc}\} = \{\mathbf{R}_{bc}^*\} = \begin{pmatrix} 16466.4 \\ -6378.187 \\ 8756.374 \\ -16466.4 \\ 2378.187 \\ 0 \end{pmatrix} \text{ [N, Nm]}$$

$$\{\mathbf{R}_{cd}\} = \begin{pmatrix} 6466.314 \\ 3621.752 \\ 0 \\ -6466.314 \\ -13621.752 \\ 0 \end{pmatrix} \xrightarrow{\text{transform}} \{\mathbf{R}_{cd}^*\} = \begin{pmatrix} 6777.19 \\ -3000 \\ 0 \\ -14777.19 \\ -3000 \\ 0 \end{pmatrix} \text{ [N, Nm]}$$

8. Kontrola rovnováhy na prutu – obr. 9.



Obrázek 9: Force equilibrium on the bar [kN, kNm]

Bar a – b

$$\begin{aligned}\sum F_x &= 0 : 6.378 + (-6.378) = 0 \\ \sum F_z &= 0 : -15.534 + 8 \cdot 4 - 16.466 = 0 \\ \sum M_a &= 0 : 10.891 - 8 \cdot \frac{4^2}{2} + (-12.756) - (-16.466) \cdot 4 = 0\end{aligned}$$

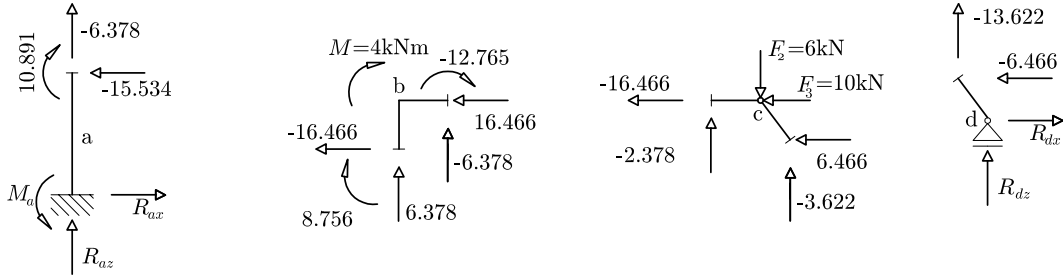
Bar b – c

$$\begin{aligned}\sum F_x &= 0 : 16.466 + (-16.466) = 0 \\ \sum F_z &= 0 : -6.378 + 4 + 2.378 = 0 \\ \sum M_b &= 0 : 8.756 - 4 \cdot 1 - 2.378 \cdot 2 = 0\end{aligned}$$

Bar c – d

$$\begin{aligned}\sum F_x &= 0 : 6.777 + 8 + (-14.777) = 0 \\ \sum F_z &= 0 : -3 + 6 + (-3) = 0 \\ \sum M_b &= 0 : 6 \cdot 2.5 + (-3) \cdot 5 = 0\end{aligned}$$

9. Kontrola rovnováhy ve styčnicích a, b a c a podporových reakcí – obr. 10.



Obrázek 10: Force equilibrium in nodes a, b, c and d [kN, kNm]

Node a

$$\begin{aligned}\sum F_{xa} &= 0 : R_{ax} - (-15.534) = 0 \Rightarrow R_{ax} = -15.534 \text{ kN} \\ \sum F_{za} &= 0 : R_{az} + (-6.378) = 0 \Rightarrow R_{az} = 6.378 \text{ kN} \\ \sum M_a &= 0 : M_a - 10.891 = 0 \Rightarrow M_a = 10.891 \text{ kNm}\end{aligned}$$

Node b

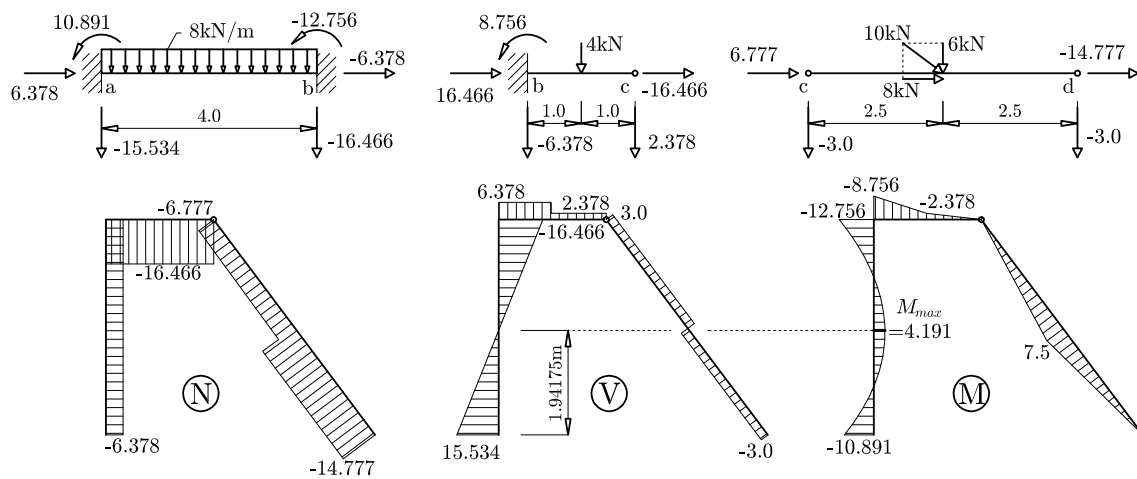
$$\begin{aligned}\sum F_{xb} &= 0 : -16.466 + 16.466 = 0 \\ \sum F_{zb} &= 0 : 6.378 + (-6.378) = 0 \\ \sum M_b &= 0 : 8.756 + 4 + (-12.765) = 0\end{aligned}$$

Node c

$$\begin{aligned}\sum F_{xc} &= 0 : -16.466 + 10 + 6.466 = 0 \\ \sum F_{zc} &= 0 : -2.378 + 6 + (-3.622) = 0\end{aligned}$$

Node d

$$\begin{aligned}\sum F_{xd} &= 0 : R_{dx} - (-6.466) = 0 \Rightarrow R_{dx} = -6.466 \text{ kN} \\ \sum F_{zd} &= 0 : R_{dz} + (-13.622) = 0 \Rightarrow R_{dz} = -13.622 \text{ kN}\end{aligned}$$



Obrázek 11: Vnitřní síly rovinného rámu – N, V, M

10. Diagramy vnitřních sil obr. 11.