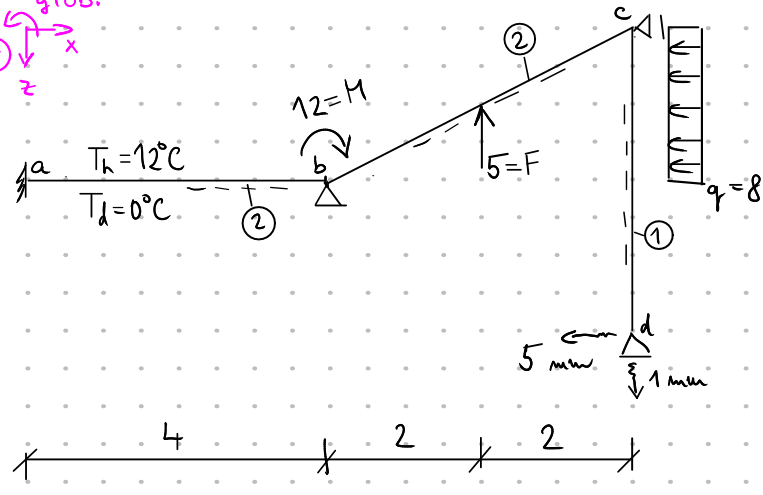
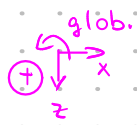
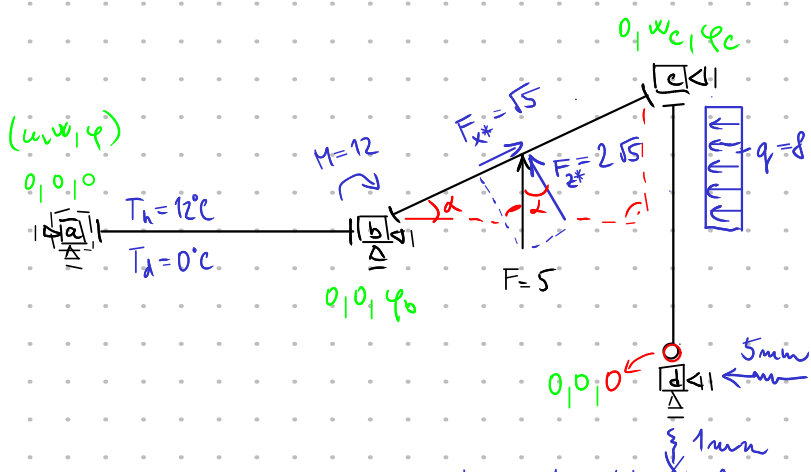




$[mm]$
 $A = 0,4 \cdot 0,6 = 0,24 m^2$
 $I_y = \frac{1}{12} b h^3 = \frac{1}{12} \cdot 0,4 \cdot 0,6^3 = 7,2 \cdot 10^{-3} m^4$
 $A = 0,4 \cdot 0,3 = 0,12 m^2$
 $I_y = \frac{1}{12} 0,4 \cdot 0,3^3 = 0,9 \cdot 10^{-3} m^4$
 $E = 24 GPa = 24 \cdot 10^6 Pa$
 $\alpha_T = 10^{-5} ^\circ C^{-1}$

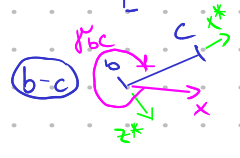


$l_{bc} = \sqrt{4^2 + 2^2} = \sqrt{20} = 2\sqrt{5} m$
 $\sin \alpha = \frac{2}{2\sqrt{5}} = \frac{\sqrt{5}}{5}$ $\cos \alpha = \frac{4}{2\sqrt{5}} = \frac{2\sqrt{5}}{5}$
 $F_{x*} = F \sin \alpha = 5 \cdot \frac{\sqrt{5}}{5} = \sqrt{5}$
 $F_{z*} = F \cos \alpha = 5 \cdot \frac{2\sqrt{5}}{5} = 2\sqrt{5}$
 1) model, $n_p = 3$.
 $\{n\} = \begin{Bmatrix} \phi_b \\ w_c \\ \phi_c \end{Bmatrix}$ $\{S\} = \begin{Bmatrix} -12 \\ 0 \\ 0 \end{Bmatrix}$

2) globalni matrice tivosti jednotlivých prutů

$(a-b)$ $a \quad b \quad x^* = x$
 $\begin{matrix} u_a \\ w_a \\ \phi_a \end{matrix}$ $\begin{matrix} u_b \\ w_b \\ \phi_b \end{matrix}$
 $r_{ab} = 0$; $s_{ab} = 0$; $c_{ab} = 1$; $t_{ab} = 8 \cdot 2a$; $E_{ab} = 24 \cdot 10^6 Pa$; $A_{ab} = 0,12 m^2$; $I_{ab} = 0,9 \cdot 10^{-3} m^4$
 $l_{ab} = 4 m$

$[k_{ab}] = \begin{bmatrix} u_a & w_a & \phi_a & u_b & w_b & \phi_b \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \end{bmatrix}$
 $\begin{matrix} 0 \\ -8,1 \\ 10,8 \\ 0 \\ 8,1 \\ 21,6 \end{matrix}$ $\begin{matrix} u_a \\ w_a \\ \phi_a \cdot 10^3 \\ u_b \\ w_b \\ \phi_b \end{matrix}$



$(b-c)$ $b \quad c \quad x^* = x$
 $\phi_{bc} \geq 270^\circ$; $s_{bc} = -\frac{\sqrt{5}}{5}$; $c_{bc} = \frac{2\sqrt{5}}{5}$; $t_{bc} = 8 \cdot 2a$; $E_{bc} = 24 \cdot 10^6 Pa$; $A_{bc} = 0,12 m^2$; $I_{bc} = 0,9 \cdot 10^{-3} m^4$
 $l_{bc} = 2\sqrt{5} m$

$[k_{bc}] = \begin{bmatrix} u_b & w_b & \phi_b & u_c & w_c & \phi_c \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \end{bmatrix}$
 $\begin{matrix} -2,897944 & 256,435853 & -2,897944 \\ -5,795888 & -131,115871 & -5,795888 \\ 19,319627 & 5,795888 & 19,319627 \\ 2,897944 & -256,435853 & 2,897944 \\ 5,795888 & 131,115871 & 5,795888 \\ 19,319627 & 5,795888 & 19,319627 \end{matrix}$ $\begin{matrix} u_b \\ w_b \\ \phi_b \cdot 10^3 \\ u_c \\ w_c \\ \phi_c \end{matrix}$

(c-d) $\delta_{cd} = 90^\circ$; $s_{cd} = 1$; $c_{cd} = 0$; $l_{ab} = 8.2 \text{ m}$; $E_{cd} = 24 \cdot 10^6 \text{ kPa}$; $A_{cd} = 0.12 \text{ m}^2$; $I_{cd} = 7.2 \cdot 10^{-3} \text{ m}^4$
 $l_{cd} = 4 \text{ m}$

pro výpočet $\tilde{R}_{cd}$

$$[k_{cd}] = \begin{bmatrix} u_c & w_c & \varphi_c & u_d & w_d & \varphi_d \\ \begin{bmatrix} 0 & 32.4 \\ 1440 & 0 \\ 0 & 129.6 \end{bmatrix} & \begin{bmatrix} -8.1 & 0 \\ 0 & -1440 \\ -32.4 & 0 \end{bmatrix} \\ \begin{bmatrix} 0 & -32.4 \\ -1440 & 0 \\ 0 & 0 \end{bmatrix} & \begin{bmatrix} 8.1 & 0 \\ 0 & 1440 \\ 0 & 0 \end{bmatrix} \end{bmatrix} \cdot 10^3$$

3) globální matice tuhosti soustavy - pro sestavení této matice a výpočet uzlových deformací potřebujeme pouze čísla $\square$

$$[k] = \begin{bmatrix} \varphi_b & w_c & \varphi_c \\ 19,319627 & 5,795888 & 9,659814 \\ +21.6 & & \\ 5,795888 & 131,115871 & 5,795888 \\ +1440 & & +0 \\ 9,659814 & 5,795888 & 19,319627 \\ +0 & & +129.6 \end{bmatrix} \cdot 10^3$$

$$[k] = \begin{bmatrix} 40,919627 & 5,795888 & 9,659814 \\ 5,795888 & 1571,115871 & 5,795888 \\ 9,659814 & 5,795888 & 148,919627 \end{bmatrix} \cdot 10^3$$

4) primární vektory koncových sil

(a-b) tab. 8.1a/10

$E_{ab} = 24 \cdot 10^6 \text{ kPa}$; $A_{ab} = 0.12 \text{ m}^2$; $I_{ab} = 0.9 \cdot 10^{-3} \text{ m}^4$
 $l_{ab} = 4 \text{ m}$

$T_h = 12^\circ \text{C}$
 $T_d = 0^\circ \text{C}$

$\Delta T_0 = (T_d + T_h)/2 = 6^\circ \text{C}$

$u_{ab} = 0.3 \text{ m}$

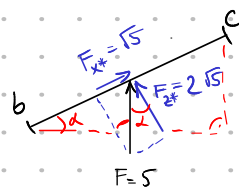
$\Delta T_1 = T_d - T_h = -12^\circ \text{C}$

$\{\bar{R}_{ab}^*\} = \{\bar{R}_{ab}\} = \{142.8; 0; -8.64; -142.8; 0; 8.64\}^T$

(b-c) tab. 8.1a/2 $s_{bc} = -\frac{\sqrt{5}}{5}$; $c_{bc} = \frac{2\sqrt{5}}{5}$; tab. 8.2a; $E_{bc} = 24 \cdot 10^6 \text{ kPa}$; $A_{bc} = 0.12 \text{ m}^2$; $I_{bc} = 0.9 \cdot 10^{-3} \text{ m}^4$; $l_{bc} = 2\sqrt{5} \text{ m}$

$\{\bar{R}_{bc}^*\} = \left\{ -\frac{\sqrt{5}}{2}; -\frac{(-2\sqrt{5})}{2}; \frac{(-2\sqrt{5}) \cdot 2\sqrt{5}}{8}; -\frac{\sqrt{5}}{2}; +\frac{2\sqrt{5}}{2}; \frac{2\sqrt{5} \cdot 2\sqrt{5}}{8} \right\}^T$

$\{\bar{R}_{bc}^*\} = \{-1.118034; 2.236068; -2.5; -1.118034; 2.236068; 2.5\}^T$



$\{\bar{R}_{bc}\} = [T_{bc}]^T \{\bar{R}_{bc}^*\} = \begin{bmatrix} 0.894427 & 0.447214 & 0 & 0 & 0 & 0 \\ -0.447214 & 0.894427 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0.894427 & -0.447214 & 0 & 0 & 0 & 0 \\ -0.447214 & 0.894427 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \end{bmatrix} \begin{Bmatrix} -1.118034 \\ 2.236068 \\ -2.5 \\ -1.118034 \\ 2.236068 \\ 2.5 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 2.5 \\ -2.5 \\ 0 \\ 2.5 \\ 2.5 \end{Bmatrix}$

$[T] = \begin{bmatrix} c & s & 0 \\ -s & c & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}$

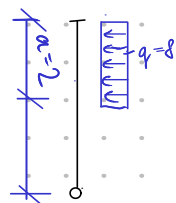
c-d) tab. 8.1b/7 $s_{cd}=1; c_{cd}=0$; tab. 8.2b; $E_{cd}=24 \cdot 10^6 \text{ Pa}$; $A_{cd}=0,24 \text{ m}^2$; $I_{cd}=7,2 \cdot 10^{-3} \text{ m}^4$; $l_{cd}=4 \text{ m}$

$$\{\bar{R}_{cd}\} = \{\bar{R}_{cd}\}_q + \{\tilde{R}_{cd}\} = \{\bar{R}_{cd}\}_q + [k_{cd}] \cdot \{\tilde{u}_{cd}\}$$

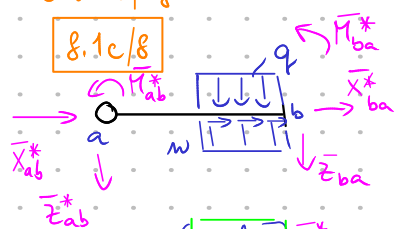
$$\{\bar{R}_{cd}^*\}_q = \begin{Bmatrix} 0 & -14,25 & 9 & 0 & -1,75 & 0 \end{Bmatrix}^T$$

$$= \begin{Bmatrix} 0 & -14,25 & 9 & 0 & -1,75 & 0 \end{Bmatrix}^T$$

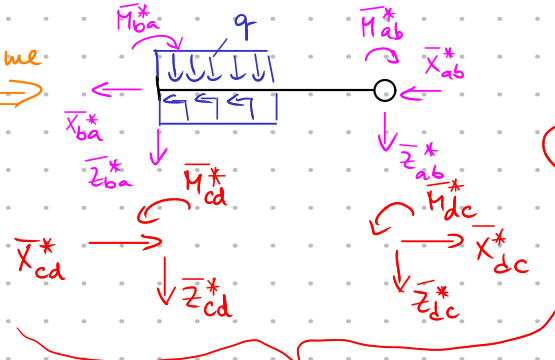
$$= \begin{Bmatrix} 0 & -14,25 & 9 & 0 & -1,75 & 0 \end{Bmatrix}^T$$



Pozn. spojíme zatížení u tohoto konce na prutu s kloubem nalezneme v tabulce



překlopíme



My chceme

$$\{\bar{R}_{ab}^*\} = \begin{Bmatrix} -\frac{ml}{8} \\ -\frac{7}{128}ql \\ 0 \\ -\frac{3}{8}ml \\ -\frac{57}{128}ql \\ \frac{9}{128}ql^2 \end{Bmatrix}$$

$$\begin{aligned} \bar{x}_{cd}^* &= -\bar{x}_{ba}^* \\ \bar{z}_{cd}^* &= \bar{z}_{ba}^* \\ \bar{m}_{cd}^* &= -\bar{m}_{ba}^* \end{aligned}$$

$$\begin{aligned} \bar{x}_{dc}^* &= -\bar{x}_{ab}^* \\ \bar{z}_{dc}^* &= \bar{z}_{ab}^* \\ \bar{m}_{dc}^* &= -\bar{m}_{ab}^* \end{aligned}$$

$$\{\bar{R}_{cd}^*\} = \begin{Bmatrix} \ominus \\ \oplus \\ \ominus \\ \oplus \\ \ominus \\ \oplus \end{Bmatrix} = \begin{Bmatrix} \frac{3}{8}ml \\ -\frac{57}{128}ql \\ \frac{9}{128}ql^2 \\ \frac{ml}{8} \\ -\frac{7}{128}ql \\ 0 \end{Bmatrix}$$

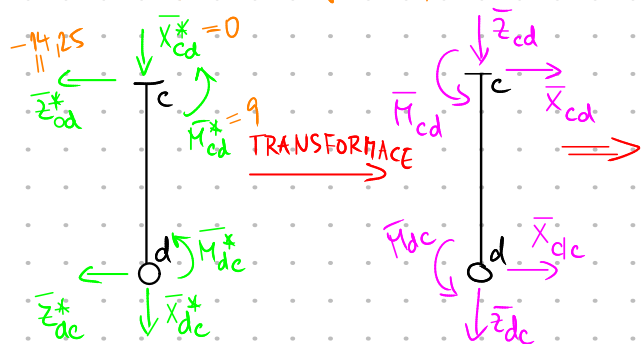
další možnost tab. 8.1b/6 - 8.1b/8

$$\{\bar{R}_{cd}^*\} = \begin{Bmatrix} -\frac{1}{2}ml + \frac{1}{8}ml \\ -\frac{5}{8}ql + \frac{23}{128}ql \\ \frac{1}{8}ql^2 - \frac{7}{128}ql^2 \\ \vdots \end{Bmatrix} = \begin{Bmatrix} -\frac{5}{8} \cdot 8 \cdot 4 + \frac{23}{128} \cdot 8 \cdot 4 \\ -\frac{5}{8} \cdot 8 \cdot 4 + \frac{23}{128} \cdot 8 \cdot 4 \\ \frac{1}{8} \cdot 8 \cdot 4^2 - \frac{7}{128} \cdot 8 \cdot 4^2 \\ \vdots \end{Bmatrix} = \begin{Bmatrix} -14,25 \\ 9 \\ -1,75 \\ \vdots \end{Bmatrix}$$

$$\{\bar{R}_{cd}^*\}_q = \begin{Bmatrix} 0 & -14,25 & 9 & 0 & -1,75 & 0 \end{Bmatrix}^T$$

$$\{\bar{R}_{cd}\}_q = [T_{cd}]^T \{\bar{R}_{cd}^*\}_q = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{Bmatrix} 0 \\ -14,25 \\ 9 \\ 0 \\ -1,75 \\ 0 \end{Bmatrix} = \begin{Bmatrix} +14,25 \\ 0 \\ 9 \\ +1,75 \\ 0 \\ 0 \end{Bmatrix}$$

Pozn. u prutu s $\varphi = 90^\circ, 180^\circ, 270^\circ$ můžeme provést transformaci pomocí náčrtku



$$\begin{aligned} \bar{x}_{cd} &= -\bar{z}_{cd}^* = -(-14,25) = 14,25 \\ \bar{z}_{cd} &= \bar{x}_{cd}^* = 0 \\ \bar{m}_{cd} &= \bar{m}_{cd}^* = 9 \\ \bar{x}_{dc} &= -\bar{z}_{dc}^* \\ \bar{z}_{dc} &= \bar{x}_{dc}^* \\ \bar{m}_{dc} &= \bar{m}_{dc}^* \end{aligned}$$

$\{\tilde{R}_{cd}\}$ - vyvolaný globální primární vektor od zadaných popuštěn podpor
 [určíme přímo globální vektor (matici máme, popuštění podpor je v globálních směrech)
 lokální vektor nepotřebujeme (nemáme lokální matici k_{cd}^* ; museli bychom provést transformaci jak k_{cd} tak $\tilde{R}_{cd}$)

vektor daných přemístění $\{\tilde{u}_{cd}\} = \{u_c, w_c, \varphi_c, u_d, w_d, \varphi_d\}^T \xrightarrow{\oplus} \begin{matrix} \leftarrow d \\ 5 \text{ mm} \leftarrow \Delta \\ \downarrow 1 \text{ mm} = w_d \\ u_d'' \end{matrix}$

$$\{\tilde{u}_{cd}\} = \{0, 0, 0, 5 \cdot 10^{-3}, 10^{-3}, 0\}^T$$

$$\{\tilde{R}_{cd}\} = [k_{cd}] \{\tilde{u}_{cd}\} = \begin{bmatrix} u_c & w_c & \varphi_c & u_d & w_d & \varphi_d \\ -8,1 & 0 & -1440 & 0 & 0 & 0 \\ 0 & -1440 & 0 & 0 & 0 & 0 \\ -32,4 & 0 & 0 & 0 & 0 & 0 \\ 8,1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1440 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \cdot 10^3 \cdot \begin{Bmatrix} u_c \\ w_c \\ \varphi_c \\ u_d \\ w_d \\ \varphi_d \end{Bmatrix} = \begin{Bmatrix} 40,5 \\ -1440 \\ 162 \\ -40,5 \\ 1440 \\ 0 \end{Bmatrix}$$

$$\{\bar{R}_{cd}\} = \{\bar{R}_{cd}\}_q + \{\tilde{R}_{cd}\} = \{54,45, -1440, 147, -38,75, 1440, 0\}^T$$

5) vektor pravé strany $\{F\} = \{S\} - \{\bar{R}\}$

$$\{F\} = \begin{Bmatrix} \varphi_b \\ w_c \\ \varphi_c \end{Bmatrix} = \begin{Bmatrix} -12 \\ 0 \\ 0 \end{Bmatrix} - \begin{Bmatrix} \bar{R}_{ab} & \bar{R}_{bc} & \bar{R}_{cd} \\ 8,64 & (-2,5) & 0 \\ 0 & 2,5 & (-1440) \\ 0 & 2,5 & 147 \end{Bmatrix} = \begin{Bmatrix} -18,14 \\ 1437,5 \\ -143,5 \end{Bmatrix}$$

6) řešená soustava $[K] \cdot \{x\} = \{F\}$

$$\begin{bmatrix} 40,919627 & 5,795888 & 9,659814 \\ 5,795888 & 1571,115871 & 5,795888 \\ 9,659814 & 5,795888 & 148,919627 \end{bmatrix} \cdot 10^3 \cdot \begin{Bmatrix} \varphi_b \\ w_c \\ \varphi_c \end{Bmatrix} = \begin{Bmatrix} -18,14 \\ 1437,5 \\ -143,5 \end{Bmatrix}$$

$$\begin{Bmatrix} \varphi_b \\ w_c \\ \varphi_c \end{Bmatrix} = \begin{Bmatrix} -0,2944 \\ 0,9204 \\ -1,18146 \end{Bmatrix} \cdot 10^{-3} \quad \begin{matrix} \text{rad} \\ \text{mm} \\ \text{rad} \end{matrix}$$

7) výpočet koncových sil (primární + sekundární)

$$\{\bar{R}_{ab}\} = \{\bar{R}_{ab}\} + \{\hat{R}_{ab}\} = \{\bar{R}_{ab}\} + [k_{ab}] \cdot \{x_{ab}\}$$

$$\{\bar{R}_{ab}\} = \begin{Bmatrix} 172,8 \\ 0 \\ -8,64 \\ -172,8 \\ 0 \\ 8,64 \end{Bmatrix} + \begin{bmatrix} u_a & w_a & \varphi_a & u_b & w_b & \varphi_b \\ 0 & -8,1 & 10,8 & 0 & 8,1 & 21,6 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \cdot 10^3 \cdot \begin{Bmatrix} u_a \\ w_a \\ \varphi_a \\ u_b \\ w_b \\ \varphi_b \end{Bmatrix} \cdot 10^{-3} = \begin{Bmatrix} 172,8 \\ 2,38704 \\ -11,82276 \\ -172,8 \\ -2,38707 \\ 2,27448 \end{Bmatrix}$$

$$\{R_{bc}\} = \{\bar{R}_{bc}\} + \{\hat{R}_{bc}\} = \{\bar{R}_{bc}\} + [R_{bc}] \cdot \{\pi_{bc}\}$$

$$\{R_{bc}\} = \begin{Bmatrix} 0 \\ 2,5 \\ -2,5 \\ 0 \\ 2,5 \\ 2,5 \end{Bmatrix} + \begin{bmatrix} u_b u_b & \varphi_b & u_c & w_c & \varphi_c \\ -2,897944 & 256,435853 & -2,897944 & -5,795888 & 9,659814 \\ -5,795888 & -131,115871 & -5,795888 & 2,897944 & 5,795888 \\ 19,319627 & 5,795888 & -256,435853 & 2,897944 & 19,319627 \\ 2,897944 & -256,435853 & 2,897944 & 5,795888 & -19,319627 \\ 5,795888 & 131,115871 & -5,795888 & 5,795888 & -19,319627 \end{bmatrix} \cdot 10^3 \cdot \begin{Bmatrix} 0 \\ 0 \\ -0,2947 \\ 0 \\ 0,9204 \\ -1,18176 \end{Bmatrix} = \begin{Bmatrix} 240,302 \\ -109,622 \\ -14,275 \\ -240,302 \\ 114,622 \\ -17,843 \end{Bmatrix}$$

$$\{R_{bc}^*\} = [T_{bc}] \cdot \{R_{bc}\} = \begin{bmatrix} 0,894427 & -0,447274 & 0 \\ +0,447274 & 0,894427 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{Bmatrix} 240,302 \\ -109,622 \\ -14,275 \\ -240,302 \\ 114,622 \\ -17,843 \end{Bmatrix} = \begin{Bmatrix} 263,957 \\ 9,418 \\ -14,275 \\ -266,194 \\ -4,946 \\ -17,843 \end{Bmatrix}$$

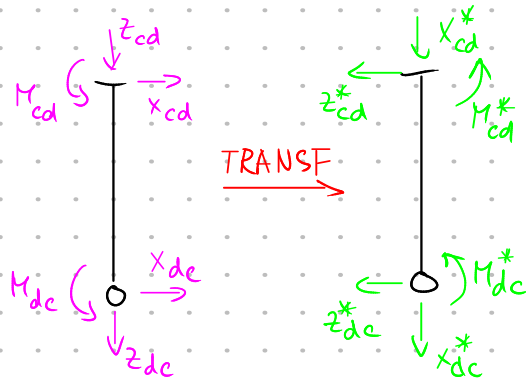
$s_{bc} = -\frac{\sqrt{5}}{5}; c_{bc} = \frac{2\sqrt{5}}{5}$

$$T_{sub} = \begin{bmatrix} c & s & 0 \\ -s & c & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

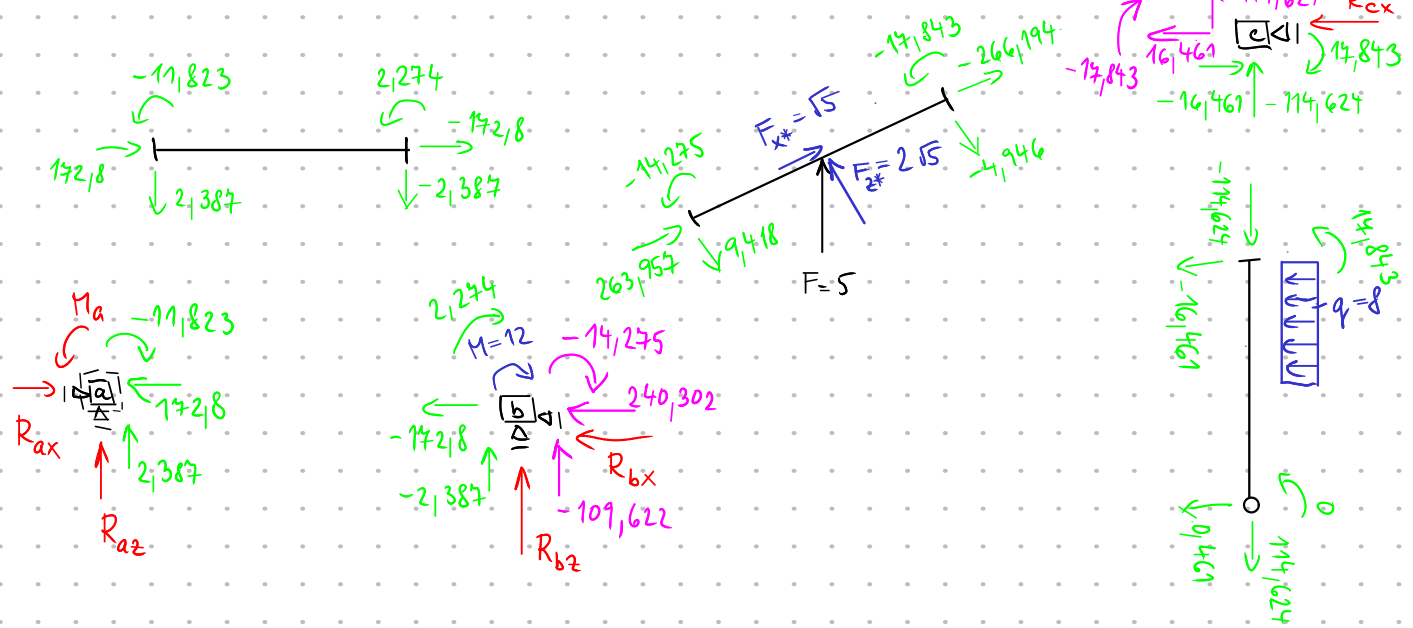
$$\{R_{cd}\} = \{\bar{R}_{cd}\} + \{\hat{R}_{cd}\} = \{\bar{R}_{cd}\} + [R_{cd}] \cdot \{\pi_{cd}\}$$

$$\{R_{cd}\} = \begin{Bmatrix} 54,75 \\ -1440 \\ 171 \\ -38,75 \\ 1440 \\ 0 \end{Bmatrix} + \begin{bmatrix} u_c & w_c & \varphi_c & u_d & w_d & \varphi_d \\ 0 & 32,4 & 0 & 0 & 0 & 0 \\ 1440 & 0 & 129,6 & 0 & 0 & 0 \\ 0 & 129,6 & -32,4 & 0 & 0 & 0 \\ 0 & 0 & -32,4 & 0 & 0 & 0 \\ -1440 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \cdot 10^3 \cdot \begin{Bmatrix} 0 \\ 0,9204 \\ -1,18176 \\ 0 \\ 0 \\ 0 \end{Bmatrix} = \begin{Bmatrix} 16,461 \\ -114,624 \\ 17,843 \\ -0,461 \\ 114,624 \\ 0 \end{Bmatrix}$$

$$\{R_{cd}^*\} = \begin{Bmatrix} -114,624 \\ -16,461 \\ 17,843 \\ 114,624 \\ +0,461 \\ 0 \end{Bmatrix}$$



8) kontrola rovnováhy na prutech a ve styčnicích (výpočet reakcí)



- provedení kontrolu a výpočet reakcí pomocí silových a momentových podmínek rovnováhy $\sum F = 0$ $\sum M = 0$

9) vykreslení vnitřních sil

