

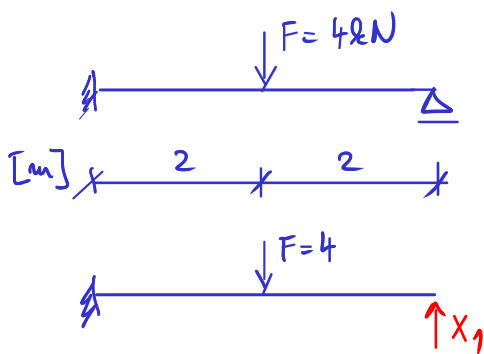
SILOVÁ METODA

- kanonická rovnice

$$\sum_{k=1}^{n_s} f_{i,k} X_k + f_{i,0} = 0$$

$i = 1, 2, \dots, n_s$

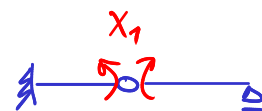
$$\begin{matrix} n_s = 2 \\ \begin{matrix} k=1 & k=2 \\ i=1 & f_{11}X_1 + f_{12}X_2 + f_{10} = 0 \\ i=2 & f_{21}X_1 + f_{22}X_2 + f_{20} = 0 \end{matrix} \end{matrix}$$



$EI = \text{konst}$

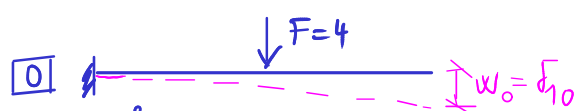
$n_s = 1$

2SUS:

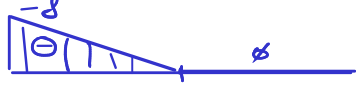


$w_1 = f_{11}$ = průhyb na konci konzoli od jednotkové síly umístěné na konci konzoli
 $w_0 = f_{10}$ = průhyb na konci konzoli od zadaného zatížení ($F=4$)

0. zatěžovací stav



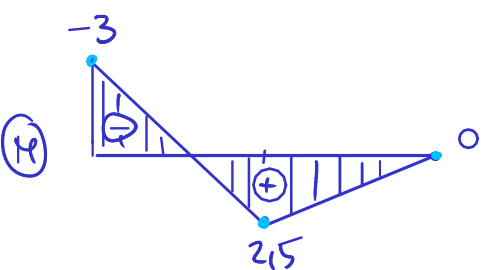
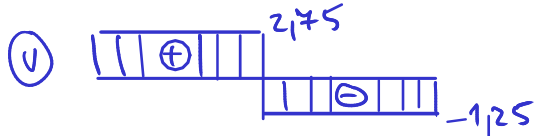
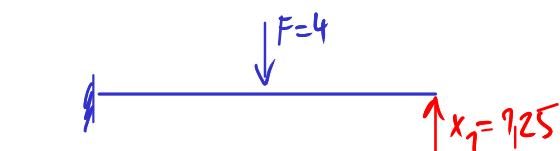
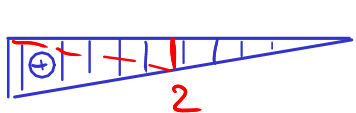
M_0



1. zatěžovací stav



M_1



$$w_1 X_1 + w_0 = 0$$

$$f_{11} X_1 + f_{10} = 0$$

$$f_{11} = \int \frac{M_1 M_1}{EI} dx = \frac{1}{EI} \left[+ \frac{1}{2} \cdot 4 \cdot 4 \cdot \left(\frac{2}{3} \cdot 4 \right) \right] = \frac{64}{3EI}$$

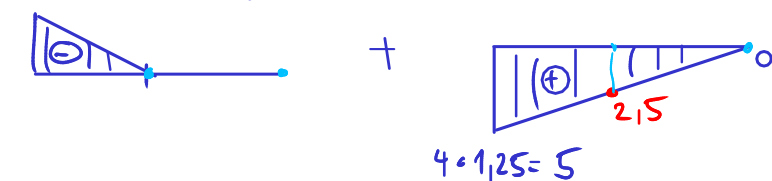
$$f_{10} = \int \frac{M_0 M_1}{EI} dx = \frac{1}{EI} \left[- \frac{1}{2} \cdot 8 \cdot 2 \cdot \left(\frac{2}{3} \cdot 4 \right) - \frac{1}{2} \cdot 8 \cdot 2 \cdot \left(\frac{1}{3} \cdot 2 \right) \right] = - \frac{80}{3EI}$$

$$\frac{64}{3EI} X_1 - \frac{80}{3EI} = 0 \quad / 3EI$$

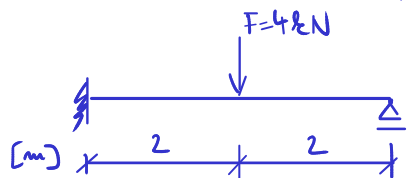
$$64 X_1 - 80 = 0$$

$$X_1 = \frac{80}{64} = \underline{\underline{1,25 \text{ kN}}}$$

(princip superpozice a úměrnosti)

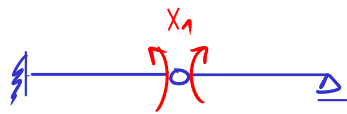


ZÁKLADNÍ SUS v podobě gerberova nosníku

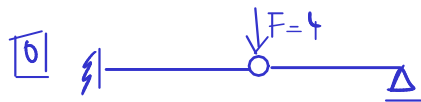


$$EI = \text{konst.}$$

$$n_s = 1$$



$$\delta_{11} X_1 + \delta_{10} = 0$$



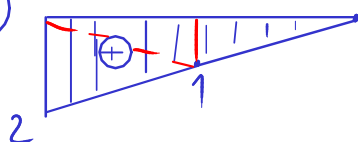
$$\delta_{11} = \frac{1}{EI} \left[+\frac{1}{2} 4 \cdot 2 \cdot \left(\frac{2}{3} 2 \right) \right] = \frac{16}{3EI}$$

M_0



$$\delta_{10} = \frac{1}{EI} \left[-\frac{1}{2} 8 \cdot 2 \cdot \left(\frac{2}{3} 2 \right) - \frac{1}{2} 8 \cdot 2 \cdot \left(\frac{1}{3} 1 \right) \right] = -\frac{40}{3EI}$$

M_1



$$\frac{16}{3EI} X_1 - \frac{40}{3EI} = 0 \quad / \cdot 3EI$$

$$X_1 = \frac{40}{16} = \underline{\underline{2,5 \text{ kNm}}}$$

$$EI = \text{konst.} \quad E_1 = E_2 = E_3 \quad I_1 = I_2 = I_3$$

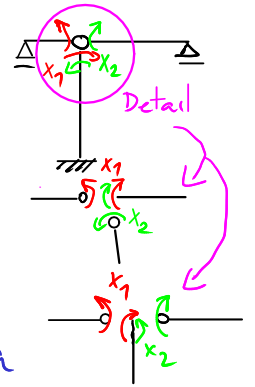
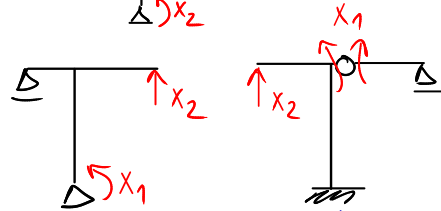
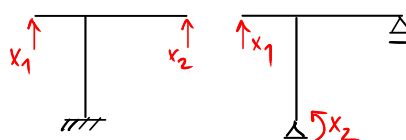
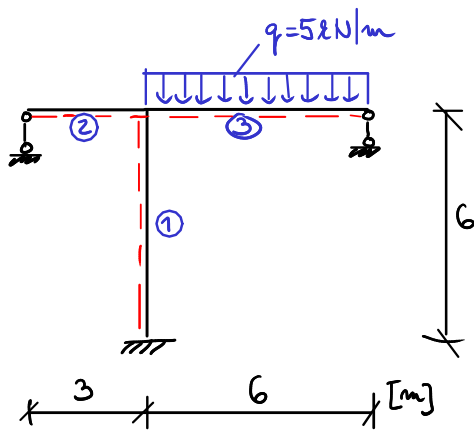
$$1) \quad m_s = 2 \quad \text{z SUS}$$

$$m_s = 2x$$

$$\text{kontrola: } m_s = 3u - p_n + (a-3)$$

$$m_s = 3 \cdot 0 - 0 + (5-3) = 2 \checkmark$$

$$1 \quad 1 \quad m_s = 5 - 3 \cdot 1 = 2 \checkmark$$



2) z SUS = lowe ma' kon a

⊕ new' nutne' resit reakce
(vykreslime z volnych koncu)

3) vnitřní síly (zauvedkame N, V)

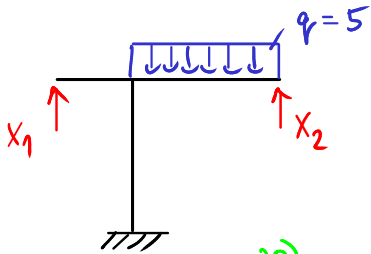
4) rovnice

$$\sum_{i=1}^{m_s} \bar{f}_{i1} x_i + \bar{f}_{10} \quad i=1, 2, \dots, m_s$$

$$\bar{f}_{11} x_1 + \bar{f}_{12} x_2 + \bar{f}_{10} = 0$$

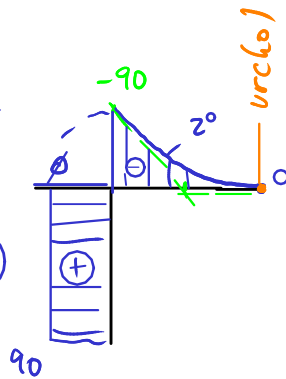
$$\bar{f}_{21} x_1 + \bar{f}_{22} x_2 + \bar{f}_{20} = 0$$

$$\begin{bmatrix} \bar{f}_{11} & \bar{f}_{12} \\ \bar{f}_{21} & \bar{f}_{22} \end{bmatrix} \begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix} + \begin{Bmatrix} \bar{f}_{10} \\ \bar{f}_{20} \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

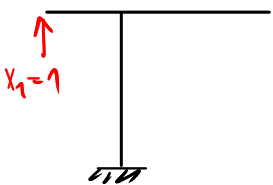


[1]

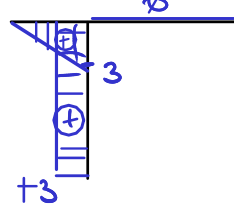
(M₀)



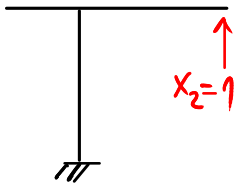
[1]



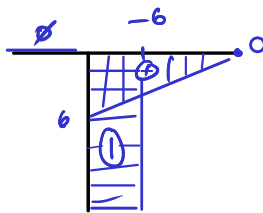
(M₁)



[2]



(M₂)



5) vyčíslení $\bar{f}$

$$\bar{f} = \int \frac{M\bar{M}}{EI} dx$$

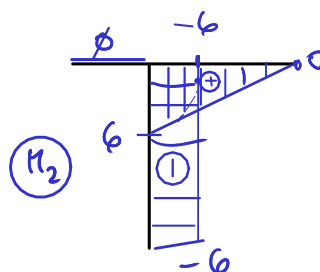
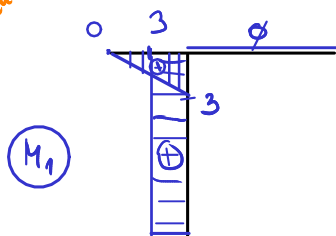
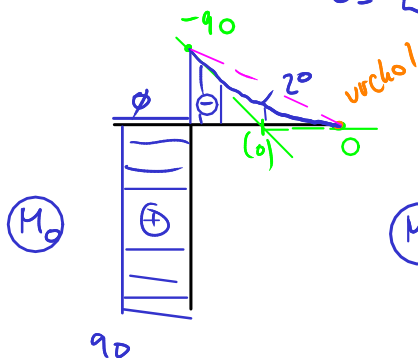
$$\bar{f}_{11} = \frac{1}{EI} \int M_1 M_1 dx = \frac{1}{EI} \left[\frac{1}{2} 3 \cdot 3 \left(\frac{2}{3} 3 \right) + 3 \cdot 6 \cdot (3) \right] = \frac{63}{EI}$$

$$\bar{f}_{22} = \frac{1}{EI} \int M_2 M_2 dx = \frac{1}{EI} \left[+ \frac{1}{2} 6 \cdot 6 \left(\frac{2}{3} 6 \right) + 6 \cdot 6 \cdot 6 \right] = \frac{288}{EI}$$

$$\bar{f}_{12} = \bar{f}_{21} = \frac{1}{EI} \int M_1 M_2 dx = \frac{1}{EI} \left[- 3 \cdot 6 \cdot 6 \right] = - \frac{108}{EI}$$

$$\bar{f}_{10} = \frac{1}{EI} \int M_0 M_1 dx = \frac{1}{EI} \left[+ 90 \cdot 6 \cdot 3 \right] = \frac{1620}{EI}$$

$$\bar{f}_{20} = \frac{1}{EI} \int M_0 M_2 dx = \frac{1}{EI} \left[- 90 \cdot 6 \cdot 6 - \frac{1}{2} 90 \cdot 6 \left(\frac{2}{3} 6 \right) + \frac{2}{3} 6 \cdot \frac{1}{8} 5 \cdot 6^2 \cdot \left(\frac{1}{2} 6 \right) \right] = - \frac{4050}{EI}$$



6) soustava rovnic

$$\bar{f}_{11} X_1 + \bar{f}_{12} X_2 + \bar{f}_{10} = 0$$

$$\bar{f}_{21} X_1 + \bar{f}_{22} X_2 + \bar{f}_{20} = 0$$

$$\frac{63}{EI} X_1 - \frac{108}{EI} X_2 + \frac{1620}{EI} = 0 \quad /EI$$

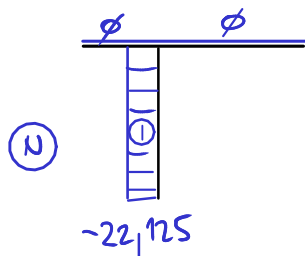
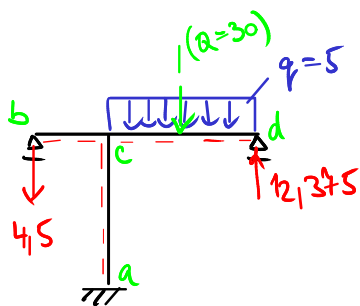
$$- \frac{108}{EI} X_1 + \frac{288}{EI} X_2 - \frac{4050}{EI} = 0 \quad /EI$$

$$63X_1 - 108X_2 + 1620 = 0$$

$$-108X_1 + 288X_2 - 4050 = 0$$

$$X_1 = -4,5 \text{ kN} \quad (\text{reakce levý kyvný prut})$$

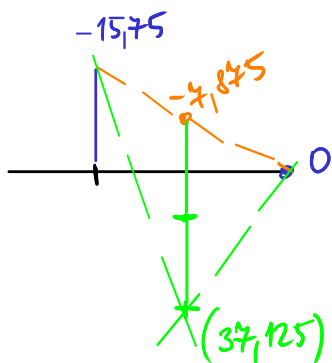
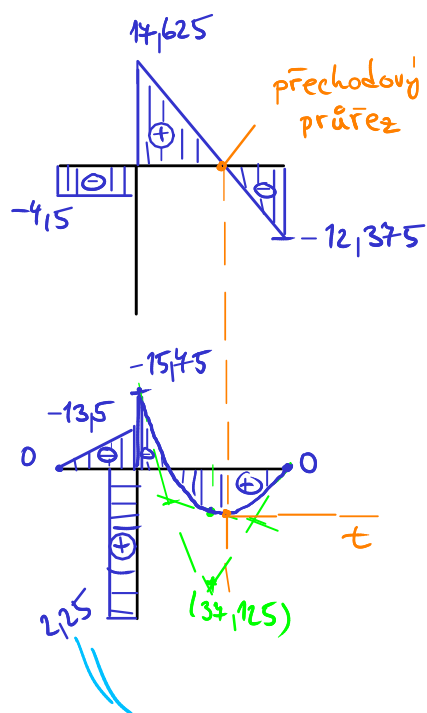
$$X_2 = 12,375 \text{ kN} \quad (\text{reakce pravý kyvný prut})$$



$$(N = N_0 + N_1 X_1 + N_2 X_2)$$

$$M = M_0 + M_1 X_1 + M_2 X_2$$

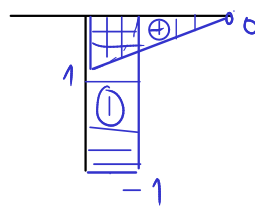
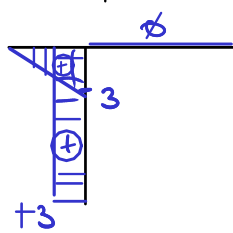
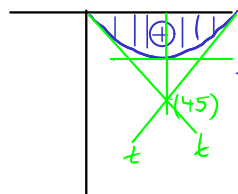
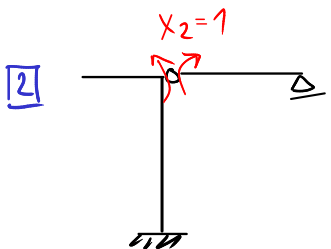
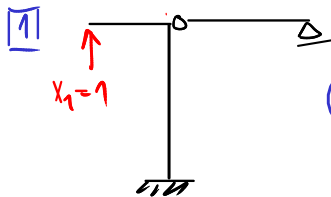
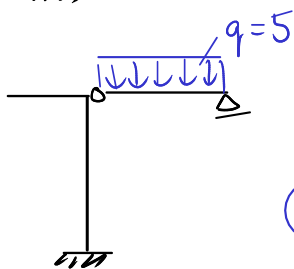
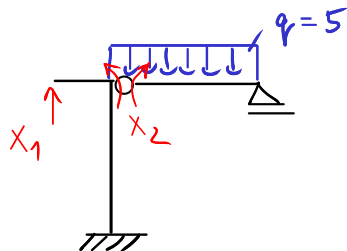
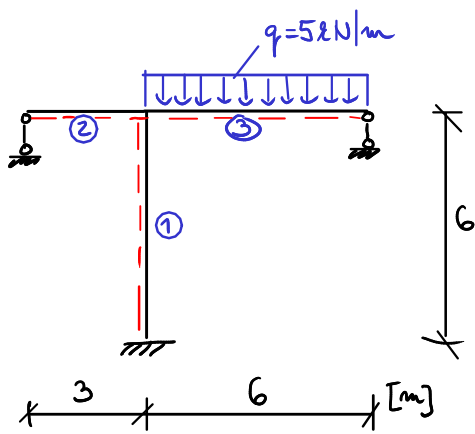
např. $M_{cd} = M_{cd} + M_{cd} X_1 + M_{cd} X_2 =$
 $= -90 + 0 \cdot (-4,5) + 6 \cdot 12,375 = -15,75$
 $\underline{\underline{22,5}}$



$$90 + 3 \cdot (-4,5) + (-6) \cdot 12,375$$

vzepětí $\frac{1}{8} q l^2 = \frac{1}{8} 5 \cdot 6^2 = 22,5$

Alternativní ZSUS



$$f_{11}X_1 + f_{12}X_2 + f_{10} = 0$$

$$f_{21}X_1 + f_{22}X_2 + f_{20} = 0$$

$$f_{11} = \frac{1}{EI} \left[+\frac{1}{2} \cdot 3 \cdot 3 \cdot \left(\frac{2}{3} \cdot 3\right) + 3 \cdot 6 \cdot 3 \right] =$$

$$= \frac{63}{EI}$$

$$f_{22} = \frac{1}{EI} \left[+\frac{1}{2} \cdot 6 \cdot 1 \cdot \left(\frac{2}{3} \cdot 1\right) + 6 \cdot 1 \cdot 1 \right] = \frac{8}{EI}$$

$$f_{12} = f_{21} = \frac{1}{EI} \left[-6 \cdot 3 \cdot 1 \right] = -\frac{18}{EI}$$

$$f_{10} = 0$$

$$f_{20} = \frac{1}{EI} \left[\frac{2}{3} \cdot 6 \cdot 22,5 \cdot \left(\frac{1}{2} \cdot 1\right) \right] = \frac{45}{EI}$$

$$63X_1 - 18X_2 = 0 \quad | \cdot 18$$

$$-18X_1 + 8X_2 + 45 = 0 \quad | \cdot 63$$

$$1134X_1 - 324X_2 = 0$$

$$-1134X_1 + 504X_2 + 2835 = 0$$

$$180X_2 = -2835$$

$$X_2 = -15,75 \text{ kNm}$$

(ohybový moment v místě vloženého kloubu)

