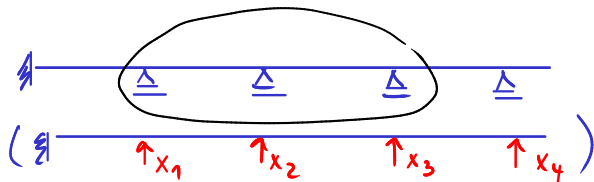
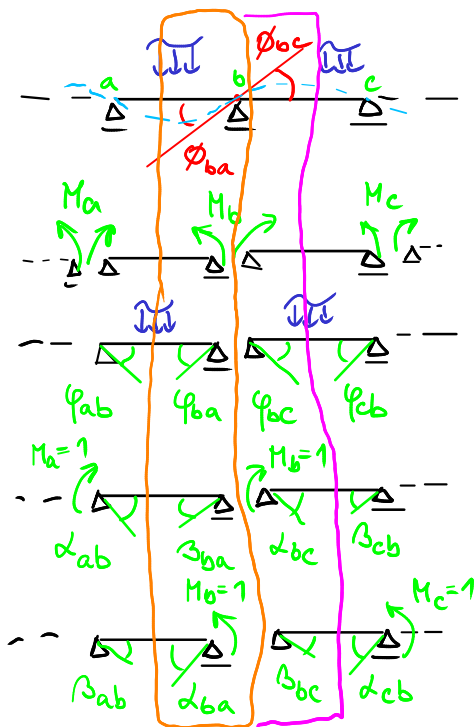


SPOJITÉ NOSNÍKY - METODA TŘÍMOMENTOVÝCH ROVNIC (MTR)



ZSUS



(+)



$$\phi_{ba} = -\phi_{bc}$$

pootočení od jednotkového protilehlého momentu

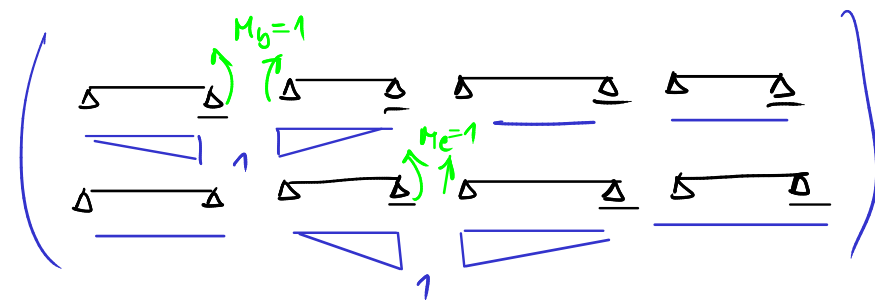
$$\phi_{ba} = \phi_{ba} + \beta_{ba} \cdot M_a + \alpha_{ba} \cdot M_b$$

↓ pootočení od zatížení

↓ pootočení od jednotkového přílehlého momentu

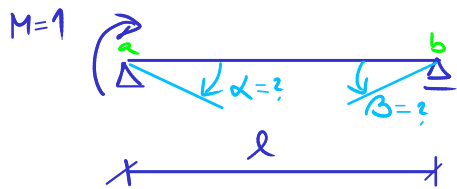
$$\phi_{bc} = \phi_{bc} + \alpha_{bc} \cdot M_b + \beta_{bc} \cdot M_c$$

$$\beta_{ba} M_a + (\alpha_{ba} + \alpha_{bc}) M_b + \beta_{bc} M_c + \phi_{ba} + \phi_{bc} = 0$$



Výpočet α a β - pootočení od jednotkového momentu

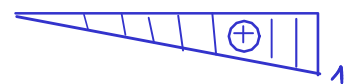
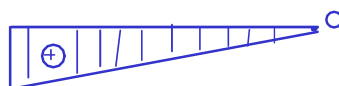
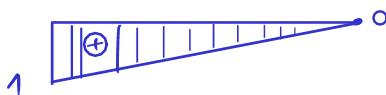
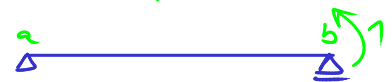
α ... přílehlý β ... protilehlý



$$\alpha = \phi_a = ?$$



$$\beta = \phi_b = ?$$



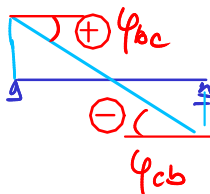
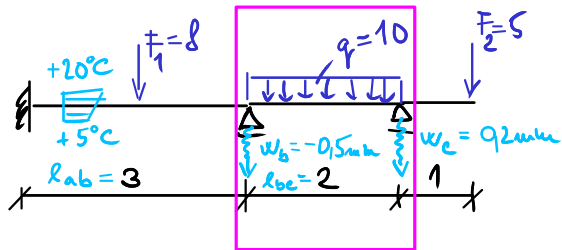
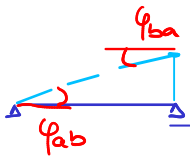
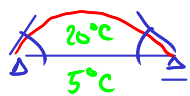
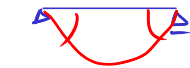
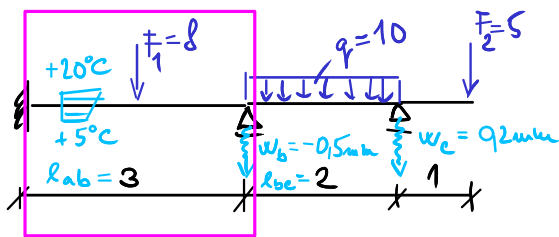
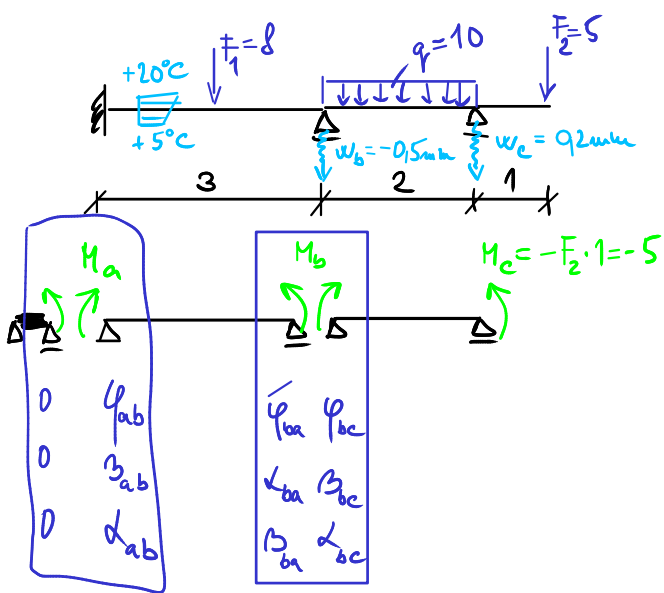
$$\alpha = \int_0^l \frac{M\bar{M}}{EI} dx = \frac{1}{EI} \left[\frac{1}{2} l \cdot 1 \cdot \left(\frac{2}{3} l \right) \right]$$

$$\alpha = \frac{l}{3EI}$$

$$\beta = \frac{1}{EI} \left[\frac{1}{2} l \cdot 1 \cdot \left(\frac{1}{3} l \right) \right]$$

$$\beta = \frac{l}{6EI}$$

[N , N/m , N/m , m]



$$\alpha_T = 10^{-5} \text{ } ^\circ\text{C}^{-1}$$

$$E = 40 \text{ GPa}$$

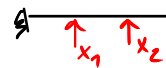
$$EI = 64000 \text{ kPa m}^4$$

$$\begin{matrix} 0,4 \\ 0,3 \end{matrix}$$

$$A =$$

$$I = \frac{1}{12} b h^3 = 1,6 \cdot 10^{-3} \text{ m}^4$$

$$1) n_s = 2$$



2) zkus z prostých nosníků, soustava rovnic

podpora (b) $\phi_{ba} = -\phi_{bc}$

$$\beta_{ba} M_a + (\alpha_{ba} + \alpha_{bc}) M_b + \beta_{bc} M_c + \phi_{ba} + \phi_{bc} = 0$$

podpora (a) $\phi_{ab} = -\phi_{ba}$ $\phi_{ao} = 0$

$$\phi_{ab} + 0 = 0 : \phi_{ab} + \beta_{ab} M_b + \alpha_{ab} M_a = 0$$

POLE a-b :

$$\alpha_{ba} = \alpha_{ab} = \frac{l_{ab}}{3EI} = \frac{3}{3EI} = \frac{1}{EI}$$

$$\beta_{ab} = \beta_{ba} = \frac{l_{ab}}{6EI} = \frac{1}{2EI}$$

$$\phi_{ab,F} = \phi_{ba,F} = \frac{F l_{ab}^2}{16EI} = \frac{8 \cdot 3^2}{16 \cdot EI} = \frac{4,5}{EI}$$

$$\phi_{ab,T} = \phi_{ba,T} = \frac{\alpha_T \Delta t_1 l_{ab}}{2} = \frac{10^{-5} \cdot (-15) \cdot 3}{2 \cdot 0,4} = -5,625 \cdot 10^{-4}$$

$$\phi_{ab,P} = \frac{w_b - w_a}{l_{ab}} = \frac{-0,5 \cdot 10^{-3} - 0}{3} = -\frac{1}{6000}$$

$$\phi_{ba,P} = \frac{w_a - w_b}{l_{ab}} = +\frac{1}{6000}$$

POLE b-c :

$$\alpha_{bc} = \alpha_{cb} = \frac{l_{bc}}{3EI} = \frac{2}{3EI}$$

$$\beta_{bc} = \beta_{cb} = \frac{l_{bc}}{6EI} = \frac{1}{3EI}$$

$$\phi_{bc,q} = \phi_{cb,q} = \frac{q l_{bc}^3}{24EI} = \frac{10 \cdot 2^3}{24 \cdot EI} = \frac{10}{3EI}$$

$$\phi_{bc,P} = \frac{w_c - w_b}{l_{bc}} = \frac{[0,2 - (-0,5)] \cdot 10^{-3}}{2} = 0,35 \cdot 10^{-3}$$

$$\left(\phi_{cb,P} = \frac{w_b - w_c}{l_{bc}} = -0,35 \cdot 10^{-3} \right)$$

$$M_a \alpha_{ab} + M_b \beta_{ab} + \varphi_{ab} = 0$$

$$M_a \beta_{ba} + M_b (\alpha_{ba} + \alpha_{bc}) + M_c \beta_{bc} + \varphi_{ba} + \varphi_{bc} = 0$$

$$\varphi_{ab} = \varphi_{ab,t} + \varphi_{ab,p} + \varphi_{ab,T}$$

$$\varphi_{bc} = \varphi_{bc,p} + \varphi_{bc,q}$$

$$M_a \cdot \frac{1}{EI} + M_b \frac{1}{2EI} - 5,625 \cdot 10^{-4} - \frac{1}{6000} + \frac{4,5}{EI} = 0$$

$$M_a \cdot \frac{1}{2EI} + M_b \left(\frac{1}{EI} + \frac{2}{3EI} \right) - 5 \cdot \frac{1}{3EI} - 5,625 \cdot 10^{-4} + \frac{1}{6000} + \frac{4,5}{EI} + 0,35 \cdot 10^{-3} + \frac{10}{3EI} = 0$$

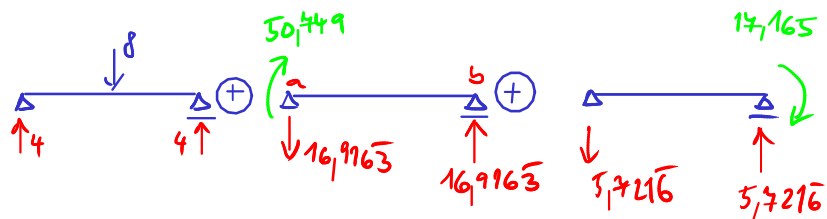
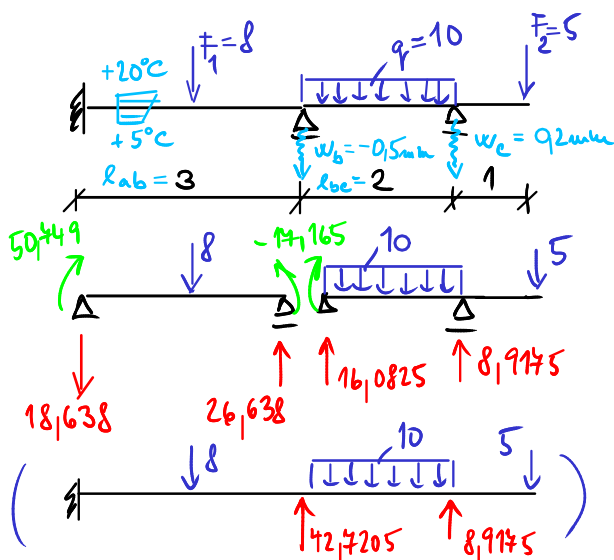
$$M_a + \frac{1}{2} M_b = 42,16$$

$$\begin{bmatrix} 1 & \frac{1}{2} \\ \frac{1}{2} & \frac{5}{3} \end{bmatrix} \begin{Bmatrix} M_a \\ M_b \end{Bmatrix} = \begin{Bmatrix} 42,16 \\ -3,23 \end{Bmatrix}$$

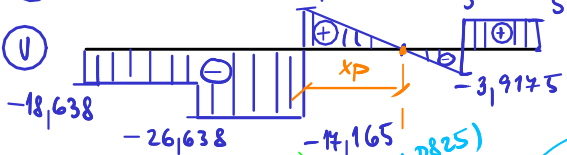
$$\frac{1}{2} M_a + \frac{5}{3} M_b = -3,23$$

$$M_b = -14,165 \text{ kNm}$$

$$M_a = 50,449 \text{ kNm}$$

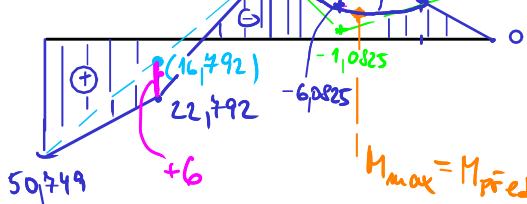
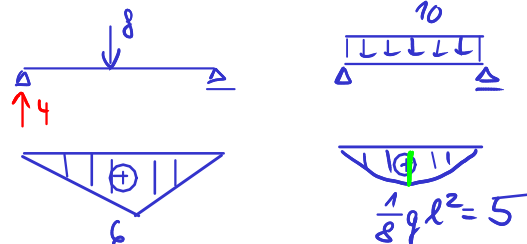


(N) = 0



$$x_p = \frac{16,0825}{9} = 1,60825 \text{ m}$$

odsunutá střednice



$$M_{\max} = M_{\text{před}} + \int_{x_p}^{\infty} v dx = -14,165 + \frac{1}{2} \cdot 1,60825 \cdot 16,0825 = -4,232 \text{ kNm}$$

$$M_{\text{před}} = \int_{x_p}^{\infty} v dx$$

zprava