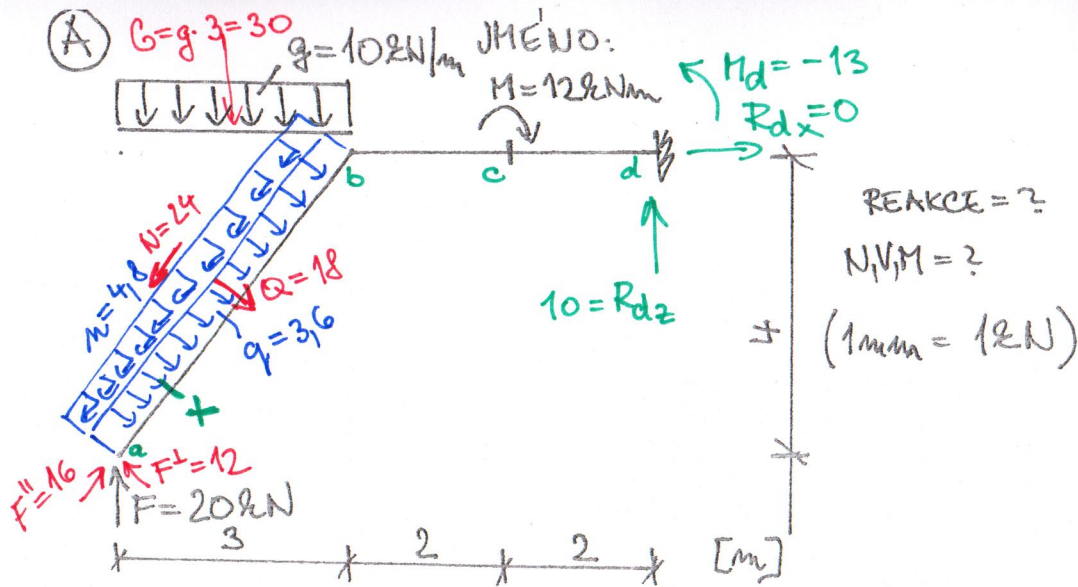




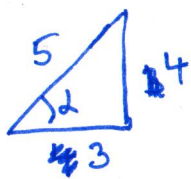
REACTION: $\sum F_{xi} = 0 \Rightarrow R_{dx} = 0$

$\sum F_{zi} = 0 \Rightarrow F - G + R_{dz} = 0 \Rightarrow R_{dz} = 10 \text{ kN}$

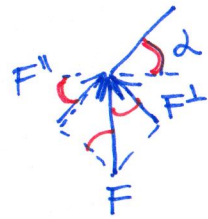
$\sum M_{di} = 0 \Rightarrow M_d - M + G \cdot 5.5 - F \cdot 4 = 0 \Rightarrow M_d = -13 \text{ kNm}$

KONTROLA: $\sum M_{bi} = 0$

$-F \cdot 3 + G \cdot 1.5 - M + M_d + R_{dz} \cdot 4 = 0 \Rightarrow 0 = 0 \checkmark$



$\sin \alpha = \frac{4}{5}$
 $\cos \alpha = \frac{3}{5}$



$F^perp = F \cdot \cos \alpha = 20 \cdot \frac{3}{5} = 12 \text{ kN}$

$F'' = F \cdot \sin \alpha = 20 \cdot \frac{4}{5} = 16 \text{ kN}$

$g' = g \cdot \cos \alpha = 10 \cdot \frac{3}{5} = 6 \text{ kN/m}$

$q = g' \cdot \cos \alpha = 6 \cdot \frac{3}{5} = 3.6 \text{ kN/m}$

$m = g' \cdot \sin \alpha = 6 \cdot \frac{4}{5} = 4.8 \text{ kN/m}$

$Q = q \cdot 5 = 18 \text{ kN}$

$N = m \cdot 5 = 24 \text{ kN}$

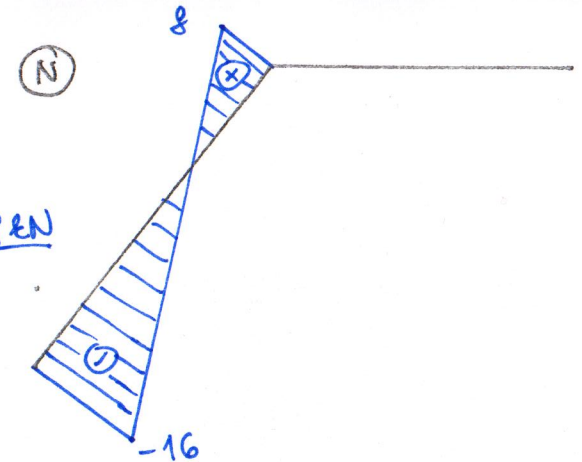
$N(x) = -16 + N_x =$

$= -16 + m \cdot x =$

$= -16 + 4.8 \cdot x$

$N(x=5) = -16 + 4.8 \cdot 5 = 8 \text{ kN}$

$N(x=0) = -16 \text{ kN}$



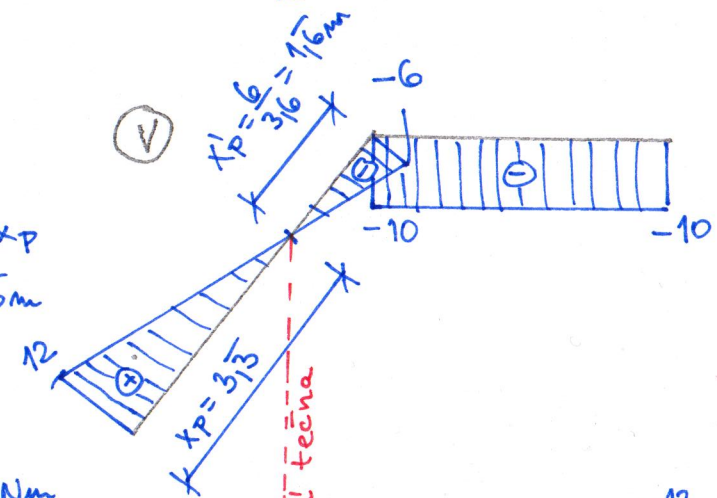
$V(x) = 12 - Q_x =$

$= 12 - q \cdot x =$

$= 12 - 3.6 \cdot x$

$V(x_p) = 0 = 12 - 3.6 \cdot x_p$

$x_p = \frac{12}{3.6} = 3.33 \text{ m}$



$M_{Q \text{ bez } q} = F \cdot 1.5 = 30 \text{ kNm}$

$M(x) = F^perp \cdot x - q \cdot \frac{x^2}{2} =$

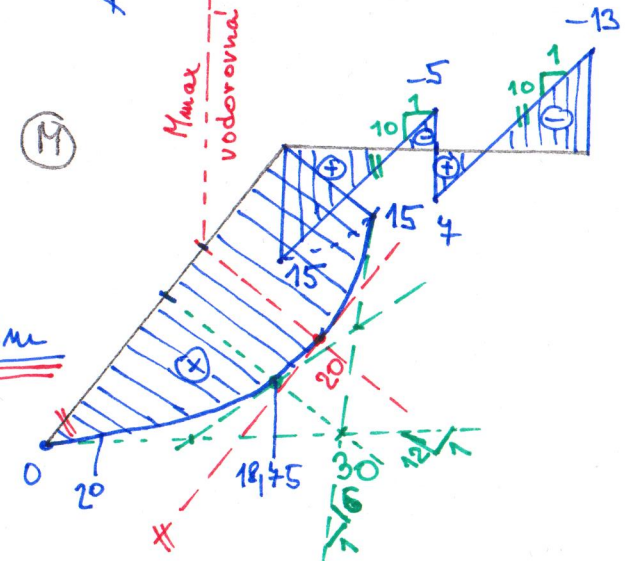
$= 12 \cdot x - 1.8 \cdot x^2$

$M(x=0) = 0 \checkmark$

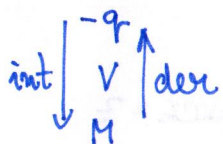
$M(x=5) = 15 \text{ kNm}$

$M_{max} = M(x=x_p) = 20 \text{ kNm}$

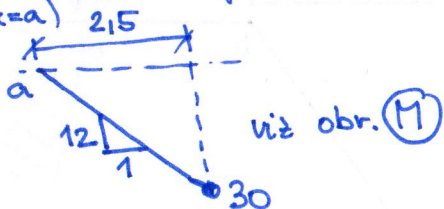
$M_Q = M(x=2.5) = 18.75 \text{ kNm}$



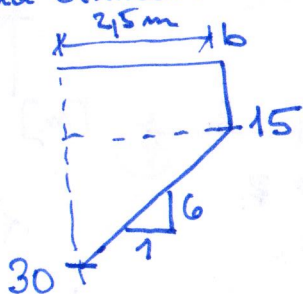
KONTROLA:



sklon tečny v bodě @ je derivace $M'(x=a)$
 což je $V(x=a)$
 $V_a = 12$



$V_b = -6$ na šikmém nosníku



- vodorovný prut

derivace M mezi $b-c$ a $c-d$ je stejná -10

(konstantní V b-d)

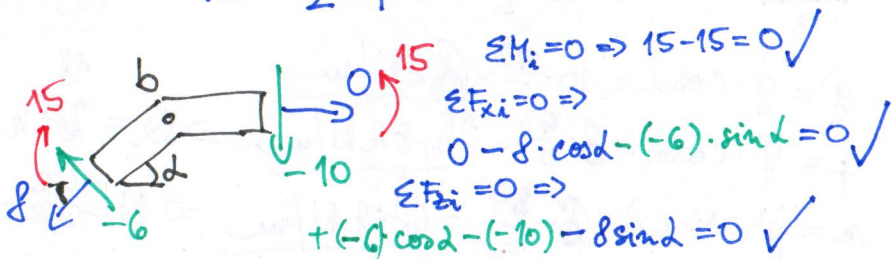
$\Rightarrow$ integrál konstanty je lineární funkce

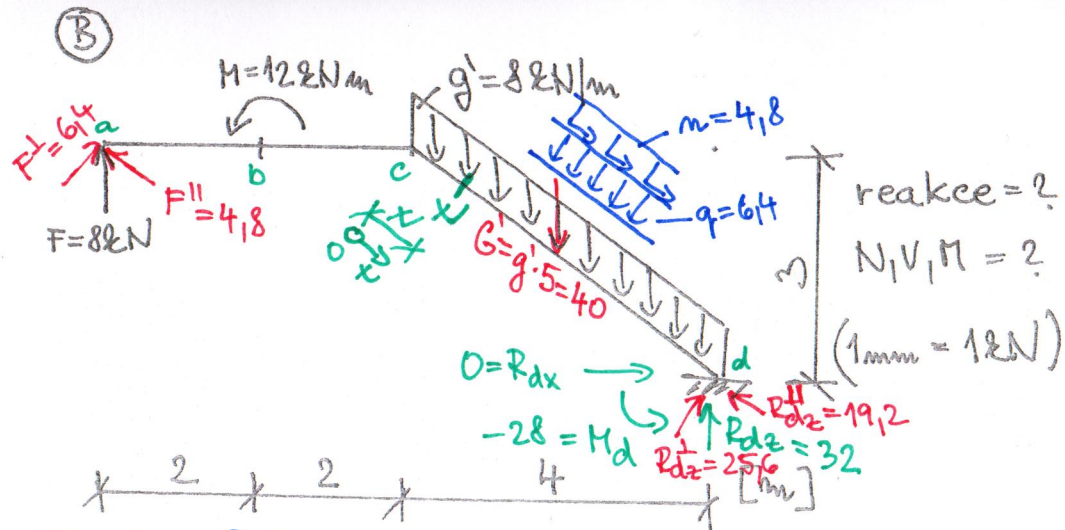
$\Rightarrow$ rovnoběžné na obou částech $b-c$ i $c-d$

$$- M_{max}^L = M_a + \int V dx = 0 + \int_0^{x_p} 12 dx = \frac{1}{2} x_p \cdot 12 = \underline{20 \text{ kNm}}$$

$$M_{max}^P = M_{ba} - \int V dx = 15 - \int_0^{x_p} (-6) dx = \underline{20 \text{ kNm}}$$

$$= 15 - \frac{1}{2} x_p (-6) = \underline{20 \text{ kNm}}$$





REAKCE: $\oplus \rightarrow$
 $\sum F_{xi} = 0 \Rightarrow R_{dx} = 0$

$\oplus \uparrow$
 $\sum F_{zi} = 0 \Rightarrow F - G' + R_{dz} = 0 \Rightarrow R_{dz} = 32 \text{ kN}$

$\oplus \curvearrowright$
 $\sum M_{di} = 0 \Rightarrow -F \cdot 8 + M + G' \cdot 2 + M_d = 0 \Rightarrow M_d = -28 \text{ kNm}$

KONTROLA: $\sum M_{ci} = 0 \oplus \curvearrowright$

$-F \cdot 4 + M - G' \cdot 2 + M_d + R_{dz} \cdot 4 + R_{dx} \cdot 3 = 0$
 $0 = 0 \checkmark$

$\sin \alpha = \frac{3}{5}$
 $\cos \alpha = \frac{4}{5}$

$g = g' \cdot \cos \alpha = 8 \cdot \frac{4}{5} = 6.4 \text{ kN/m}$

$m = g' \cdot \sin \alpha = 8 \cdot \frac{3}{5} = 4.8 \text{ kN/m}$

$Q = q \cdot 5 = 32 \text{ kN}$

$N = m \cdot 5 = 24 \text{ kN}$

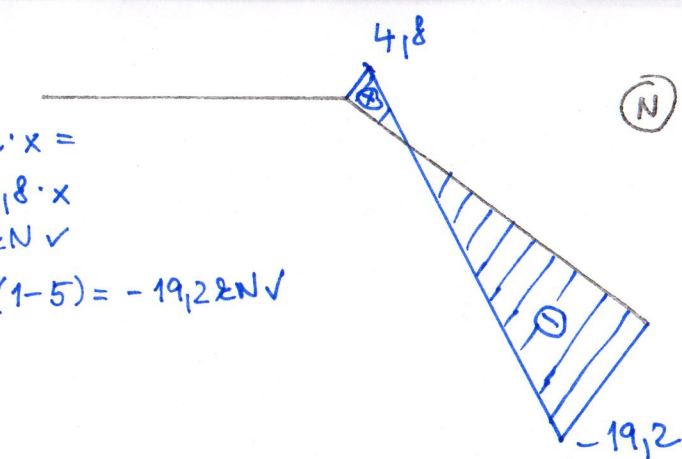
$R_{dz}^I = R_{dz} \cdot \cos \alpha = 32 \cdot \frac{4}{5} = 25.6 \text{ kN}$

$R_{dz}^{II} = R_{dz} \cdot \sin \alpha = 32 \cdot \frac{3}{5} = 19.2 \text{ kN}$

- pro vykreslování z volného konce:

$F^I = F \cdot \cos \alpha = 8 \cdot \frac{4}{5} = 6.4 \text{ kN}$
 $F^{II} = F \cdot \sin \alpha = 8 \cdot \frac{3}{5} = 4.8 \text{ kN}$

$N(x) = F^I - m \cdot x =$
 $= 4.8 - 4.8 \cdot x$
 $N(x=0) = 4.8 \text{ kN} \checkmark$
 $N(x=5) = 4.8 \cdot (1-5) = -19.2 \text{ kN} \checkmark$

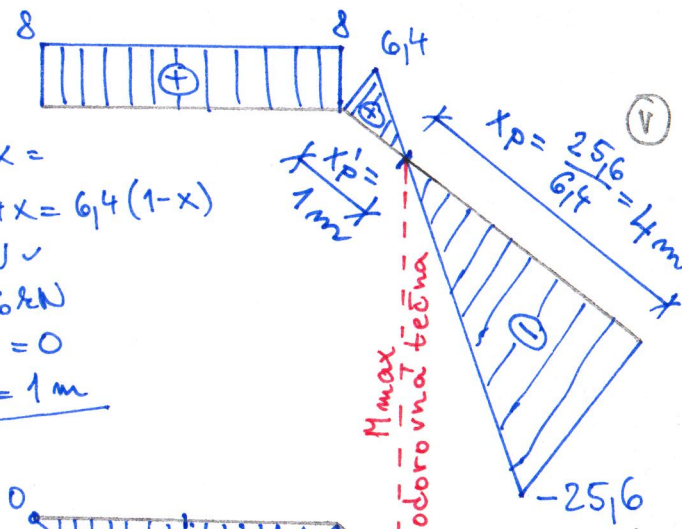


$V(x) = F^I - q \cdot x =$
 $= 6.4 - 6.4 \cdot x = 6.4(1-x)$

$V(x=0) = 6.4 \text{ kN} \checkmark$

$V(x=5) = -25.6 \text{ kN}$

$x_p: 6.4 \cdot (1-x_p) = 0$
 $x_p = 1 \text{ m}$



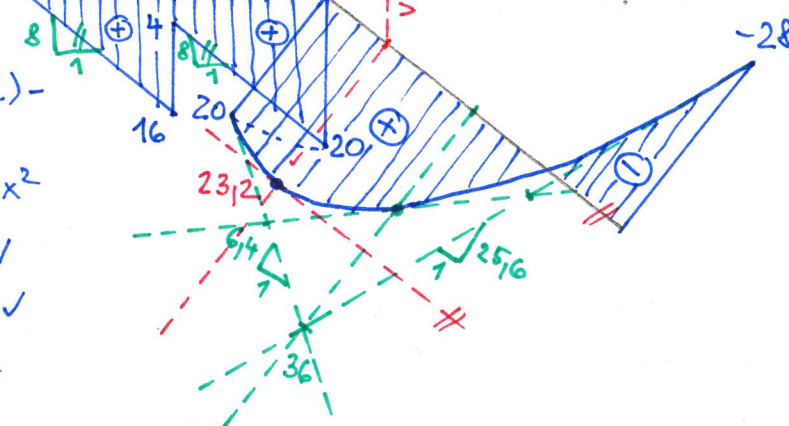
$M_{bez q} = F \cdot 6 - M = 0$
 $= 36 \text{ kNm}$

$M(x) = F \cdot (4+x \cdot \cos \alpha) -$
 $-M - q \cdot \frac{x^2}{2} =$
 $= 20 + 6.4x - 3.2x^2$

$M(x=0) = 20 \text{ kNm} \checkmark$

$M(x=5) = -28 \text{ kNm} \checkmark$

$M_{max} = M(x=x_p) =$
 $= 23.2 \text{ kNm}$



rychlá kontrola momentů

- zleva

$$M_{\max}^L = M_c + \int V dx = 20 + \begin{array}{c} 6,4 \\ \triangle \\ x_p \end{array} =$$

$$= 20 + \frac{1}{2} 6,4 \cdot 1 = \underline{23,2 \text{ kNm}} \checkmark$$

- zprava

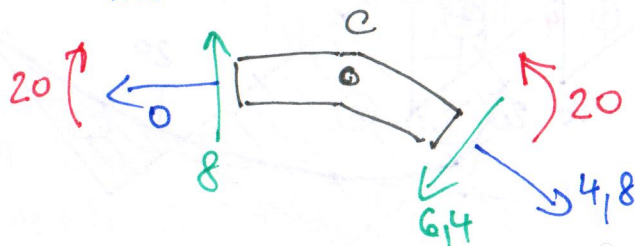
$$M_{\max}^P = M_d - \int V dx = -28 - \begin{array}{c} -25,6 \\ \triangle \\ x_p \end{array} =$$

$$= -28 - \frac{1}{2} (-25,6) \cdot 4 = \underline{23,2 \text{ kNm}} \checkmark$$

- jelikož mám rozklad ~~si~~ všech sil do směrů x a z a do směrů $\perp$ a $\parallel$

mohu provést kontrolu zleva/zprava pomocí těchto sil

- nebo bych mohl provést kontrolu na uvolněném styčnicku (c)



$$\sum M_c = 0$$

$$\sum F_x = 0$$

$$\sum F_z = 0$$